
A general notion of interiority

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FCT Fundação para a Ciência e a Tecnologia
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two issues...

▷ Introduction
Interiority
Separability index
Convexity criterion
Auto-interiority

two issues...

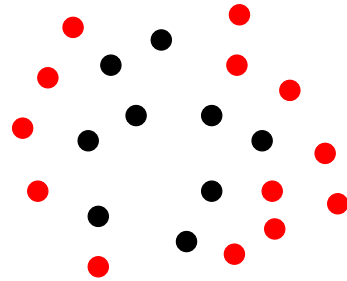
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□ to what extent a set of entities $\{\bullet\}$ is separated from \bullet ?

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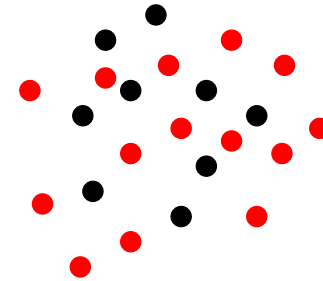
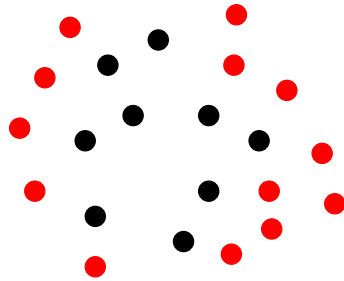
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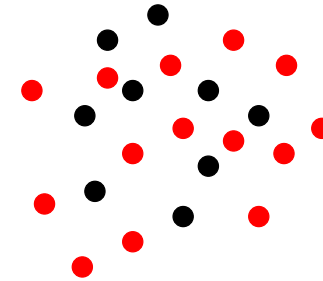
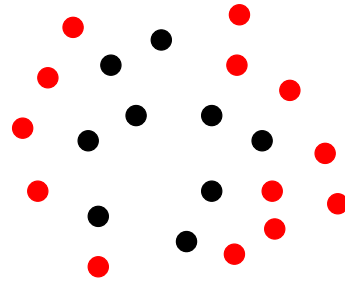
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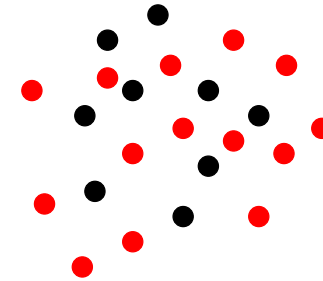
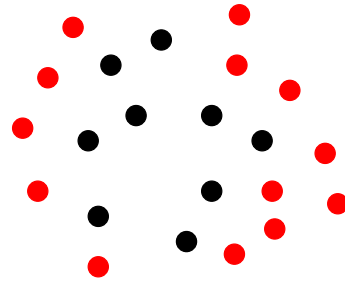


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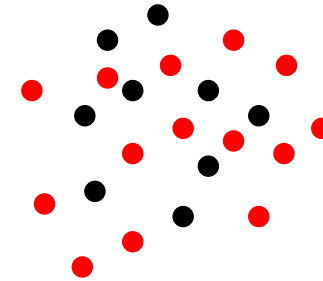
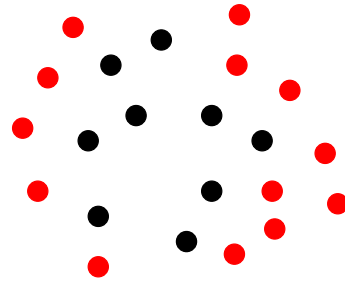


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(more concentrated to the "interior" or dispersed on the "margins" of their range)

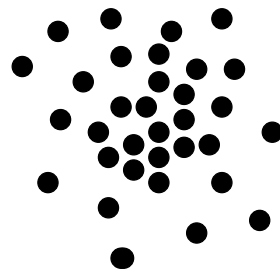
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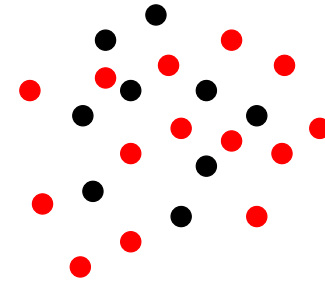
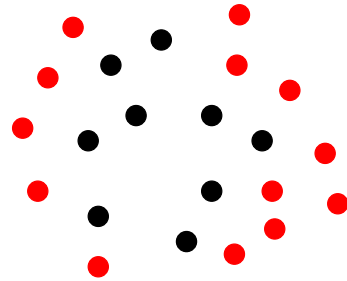
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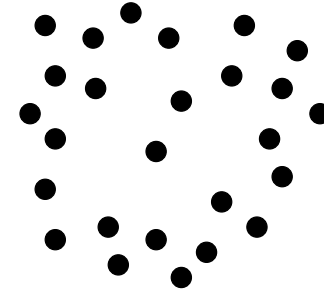
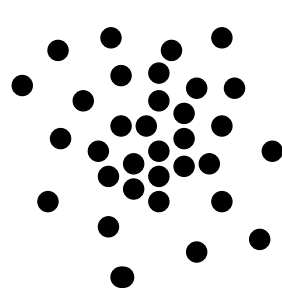
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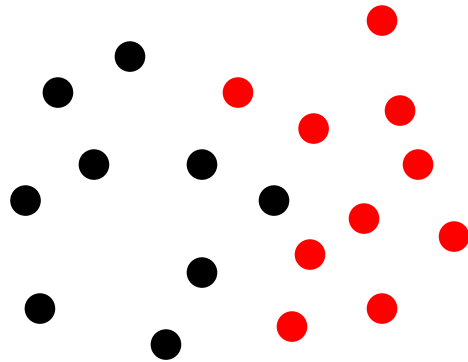
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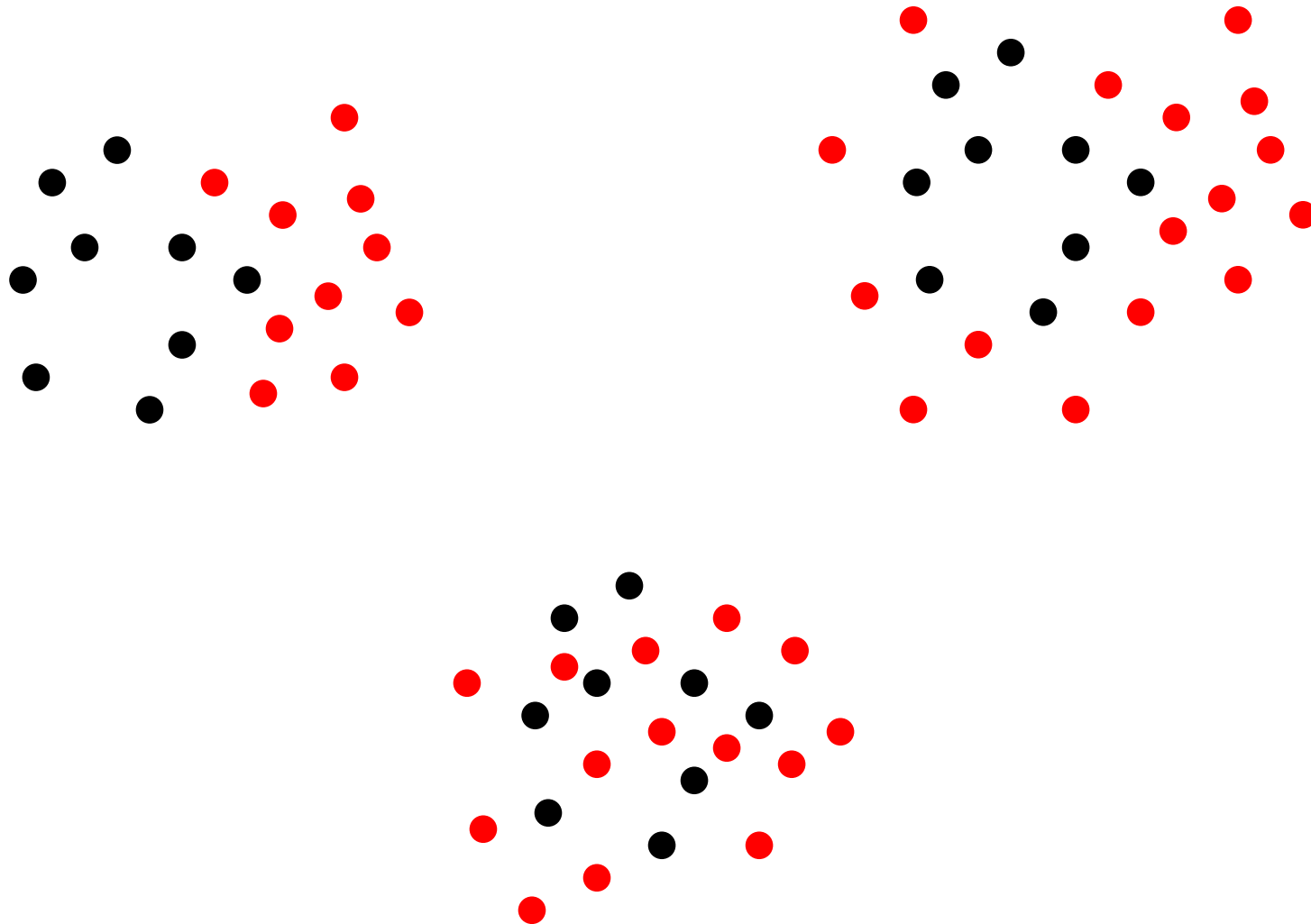
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In many areas ...

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Ecology, Chemistry, Molecular Biology, Physiology, Toxicology,
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issue:

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In the context of cluster analysis...

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methods have been proposed that measure overlap/separability of clusters as part of assessing the quality of a given partition.

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- all, except Thornton's index, are expressions that explicitly involve numerical dissimilarities between entities
- notions such as “perfect separation of cluster” are not comprise.

To construct the silhouette $S(X)$ (with respect to \bar{X}), for $i \in X$

$$S(i) = \frac{b(i) - a(i)}{\max\{a(i), b(i)\}}$$

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Thornton's index

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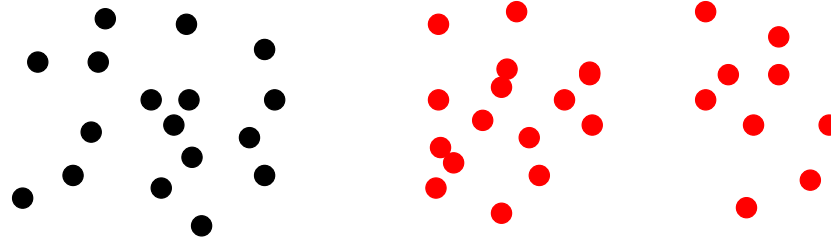
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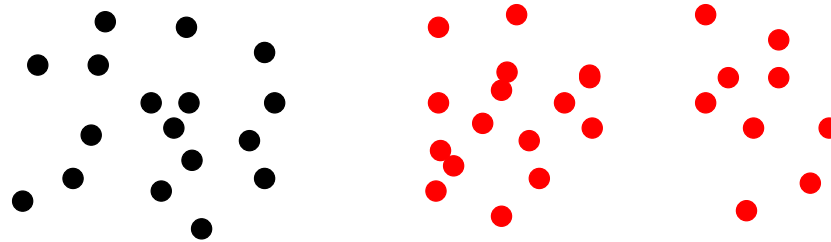
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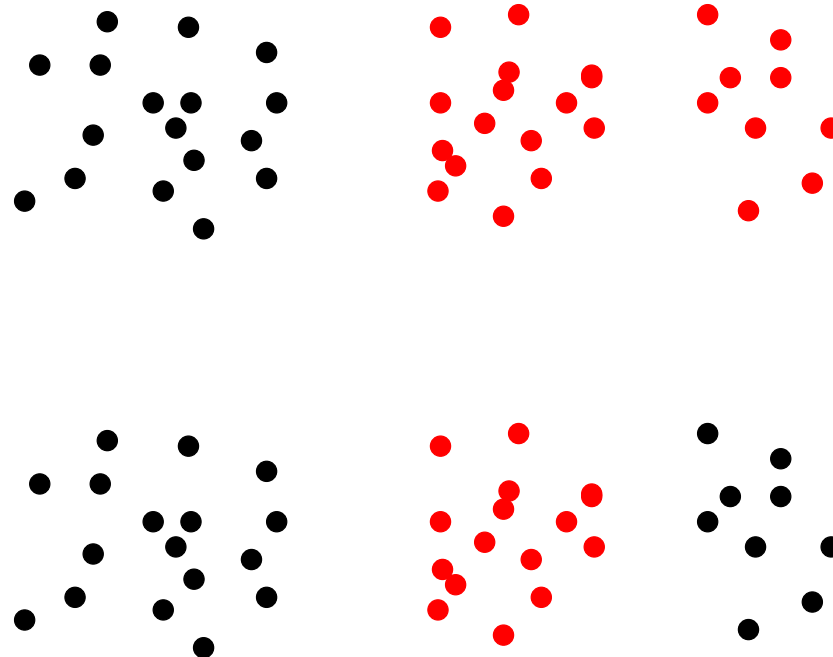


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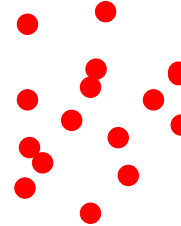
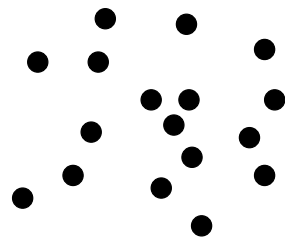


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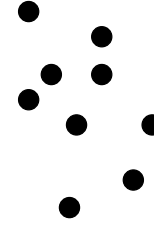
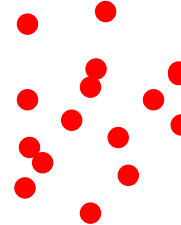
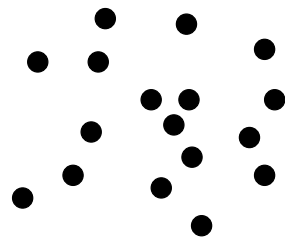
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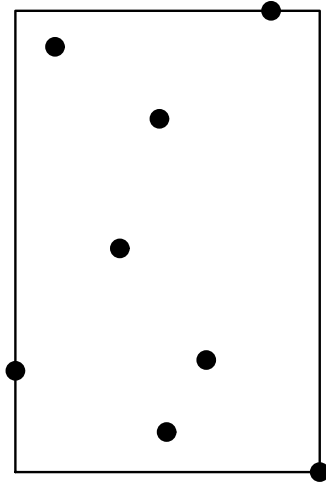
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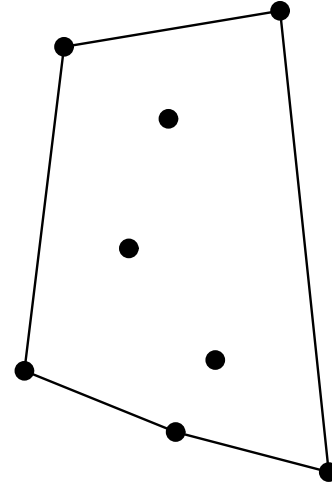
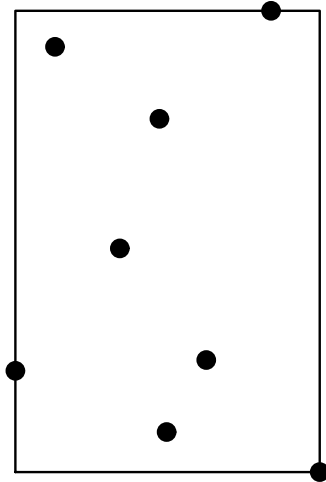
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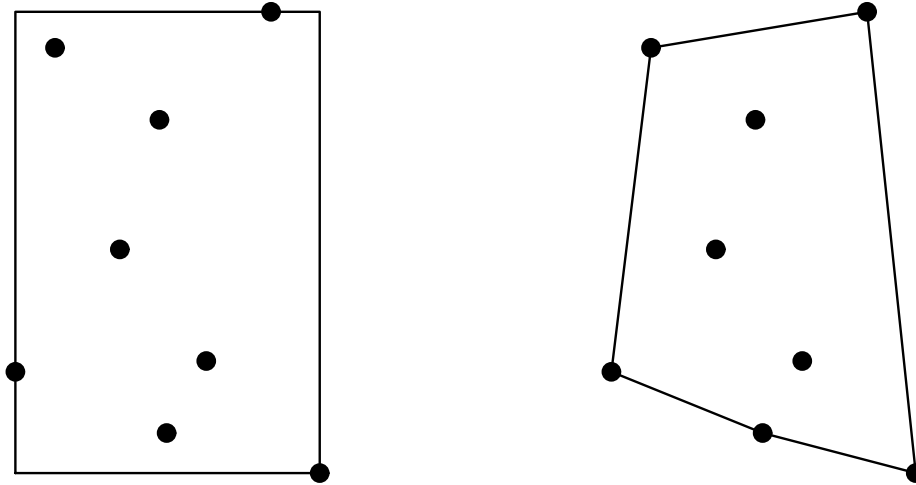
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doesn't discriminate separability

Instead of deeming...

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to what extent a set of entities X is separated from other entities?

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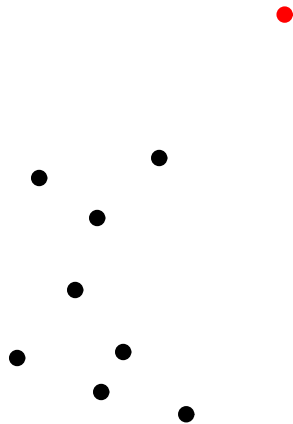
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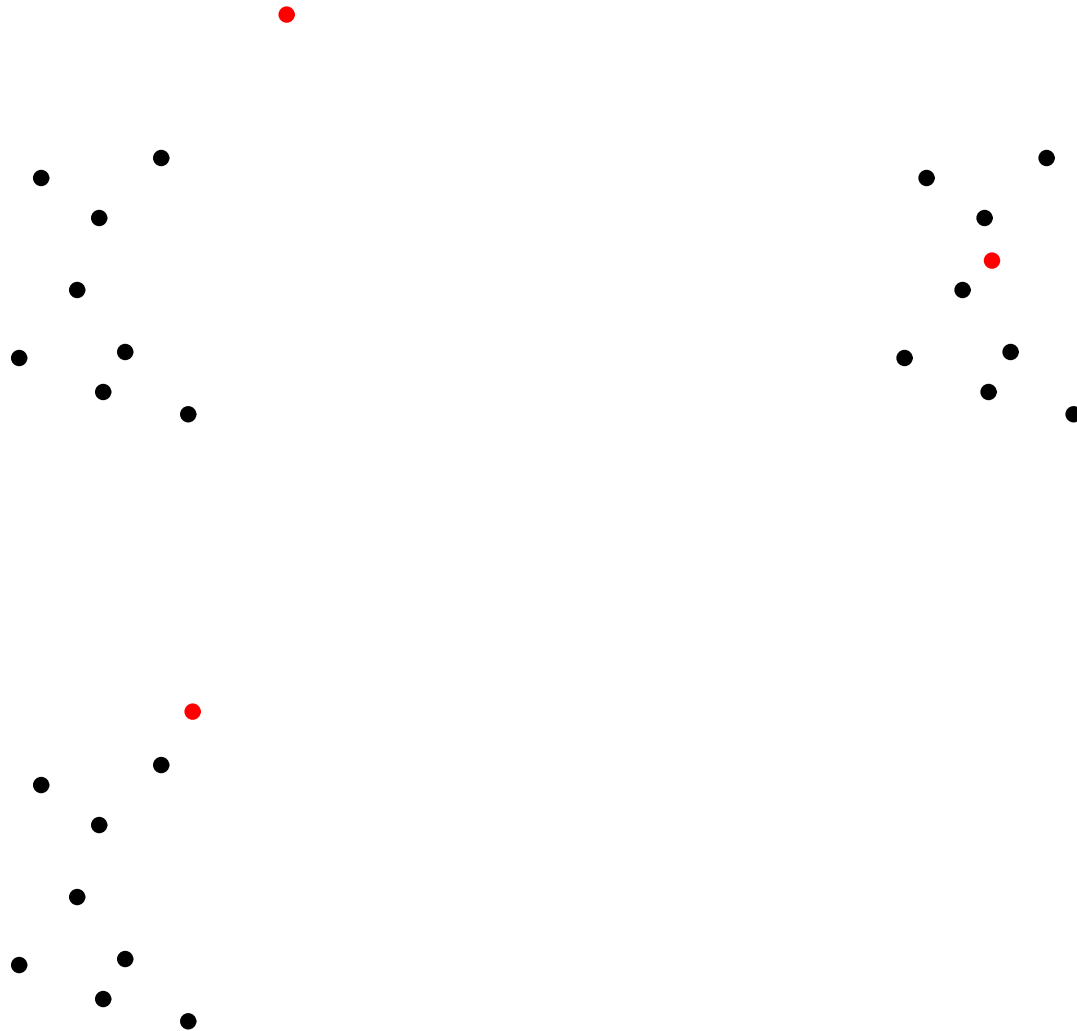
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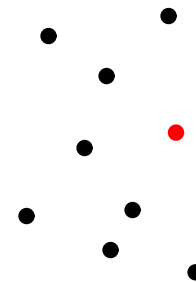
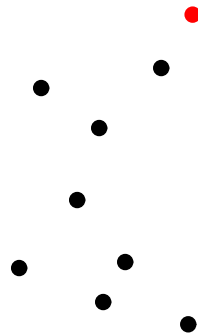
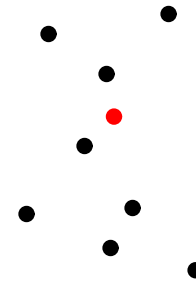
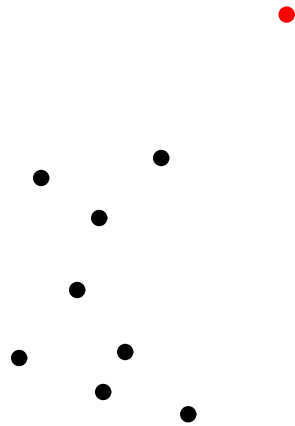
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to formalize interiority needs fixing some aggregation criterion

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i.e., a rule that identifies, for a set of entities E and $1 \leq k \leq |E|$, the k -partitions of E which are *adequately* aggregated

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- if clusters are the connected components of some minimum $(|E| - k)$ -spanning forest

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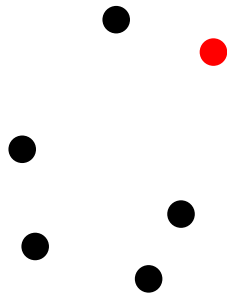
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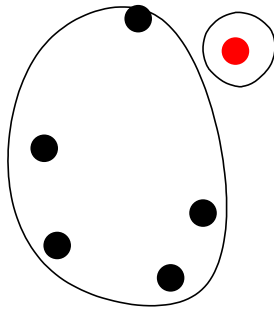
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- ☐ ...

entity \bar{x} is *k-interior* with respect to X if for every k -partition \mathcal{P}_k of X , $\mathcal{P}_k \cup \{\{\bar{x}\}\}$ is not an adequate $(k+1)$ -partition of $X \cup \{\bar{x}\}$

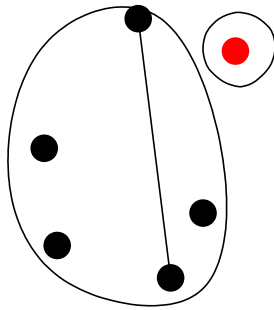
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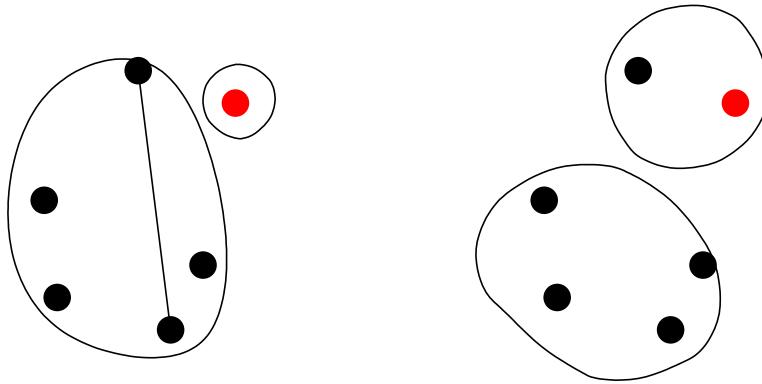
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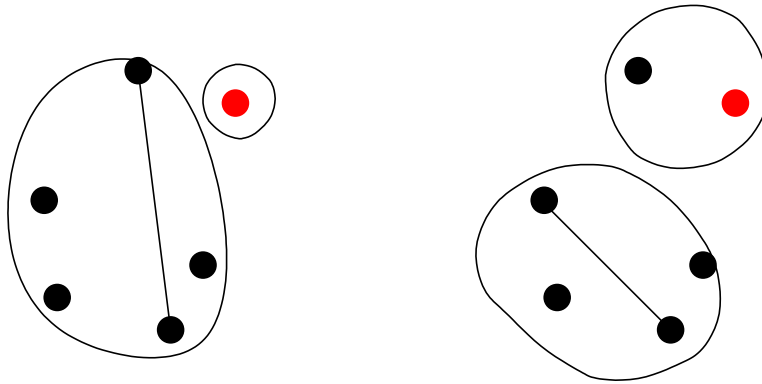
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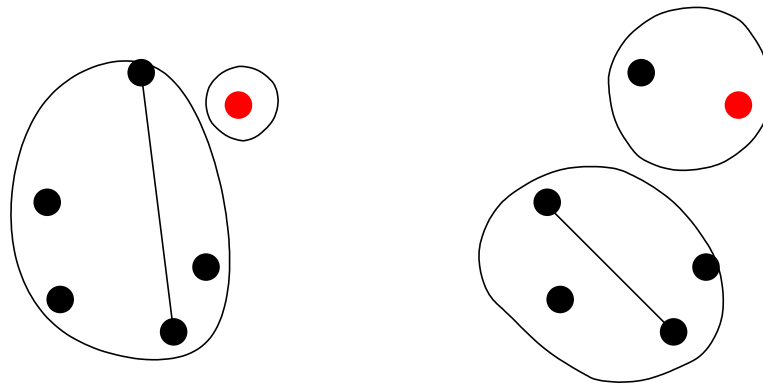
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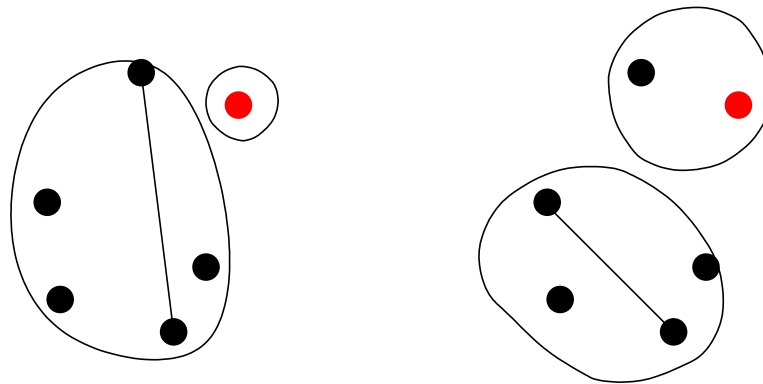


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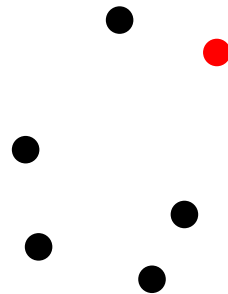


• is 1-interior

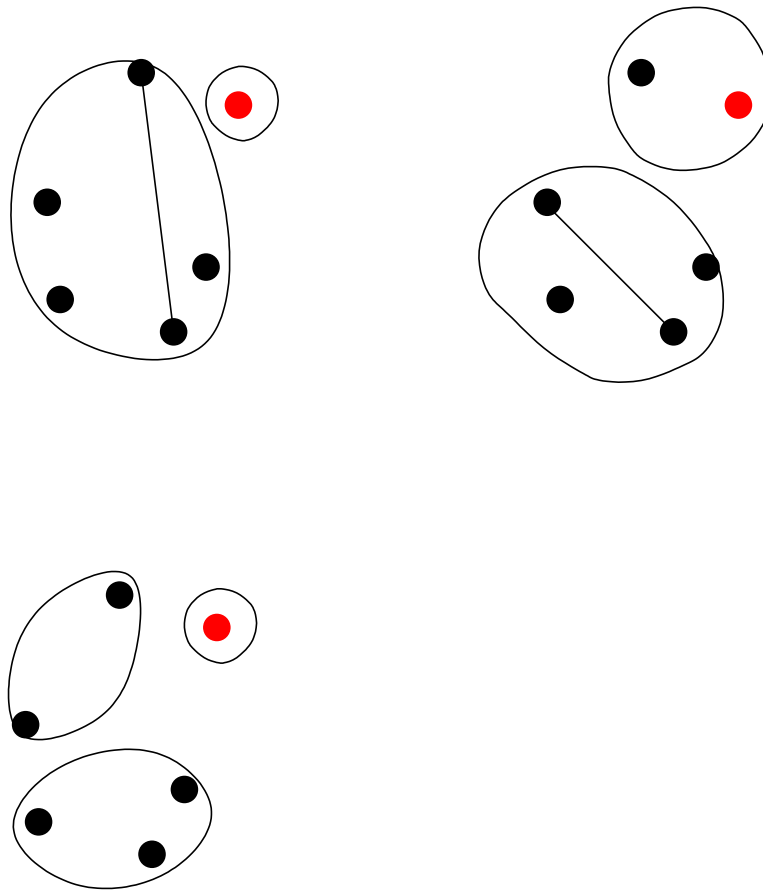
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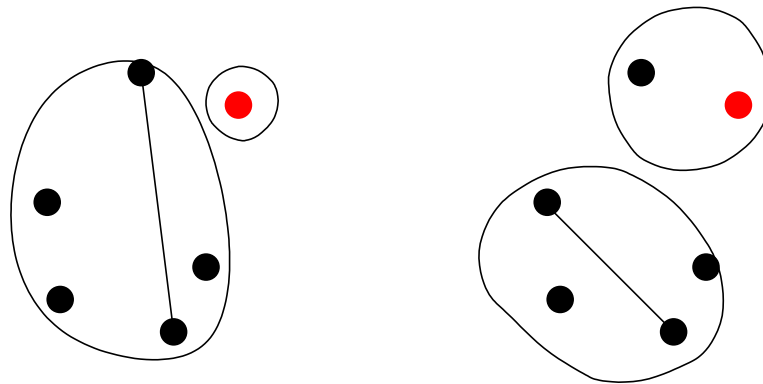


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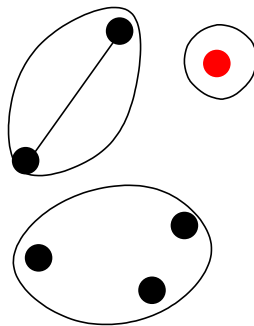


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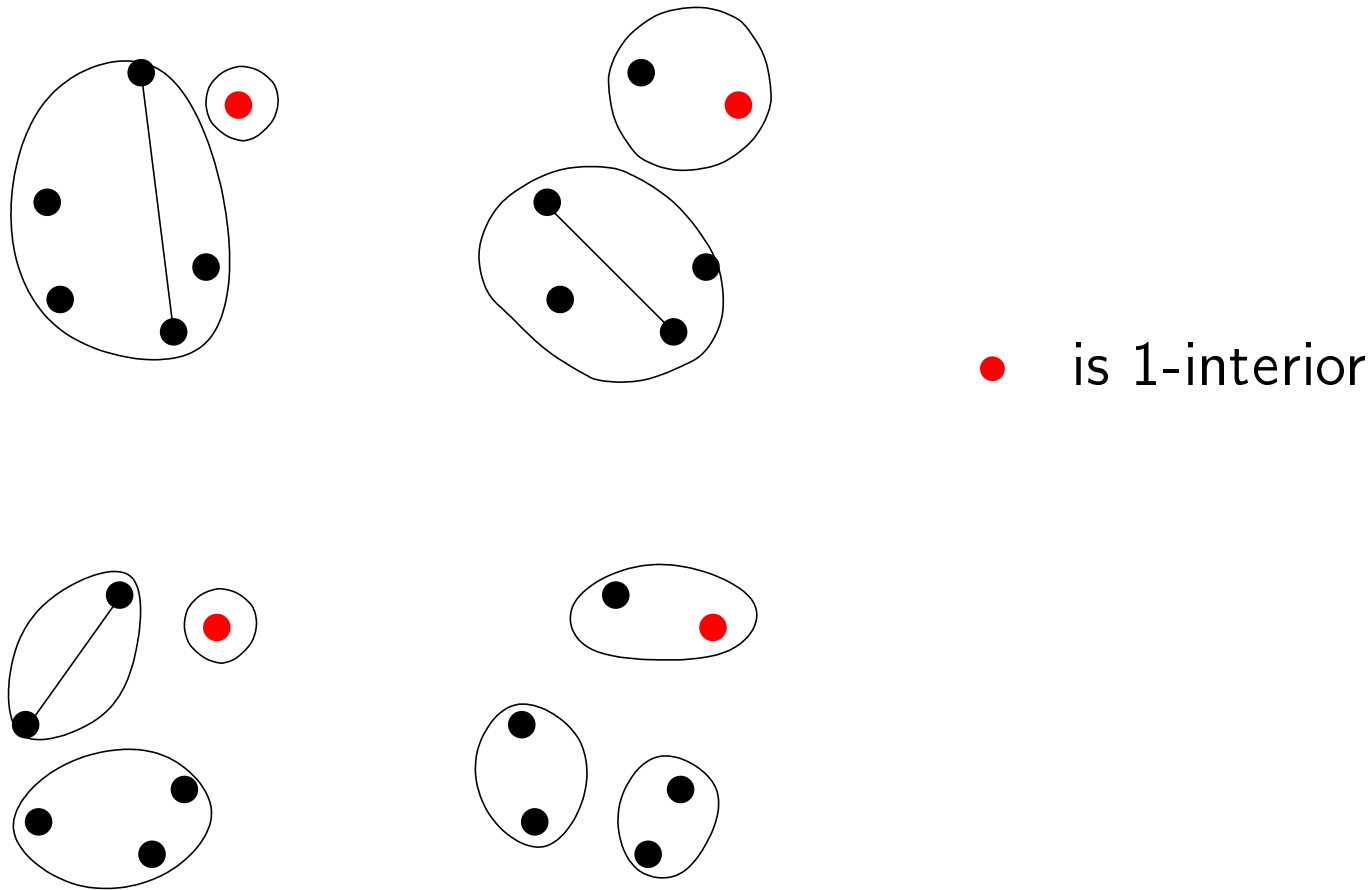
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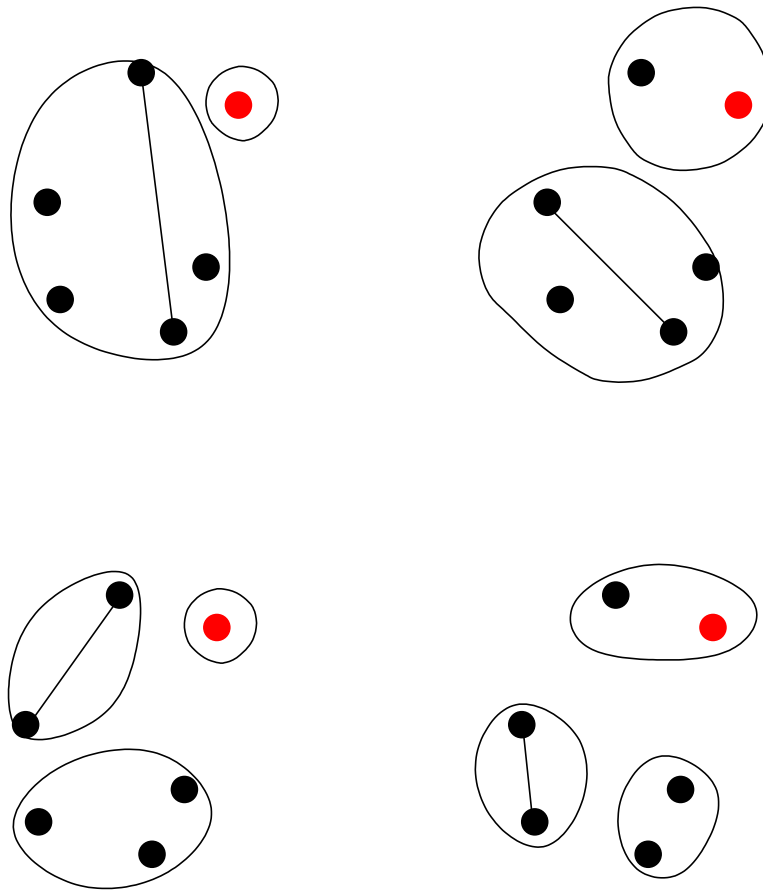
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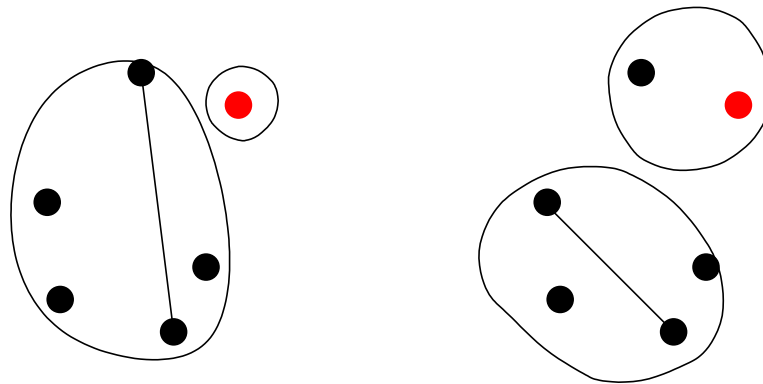


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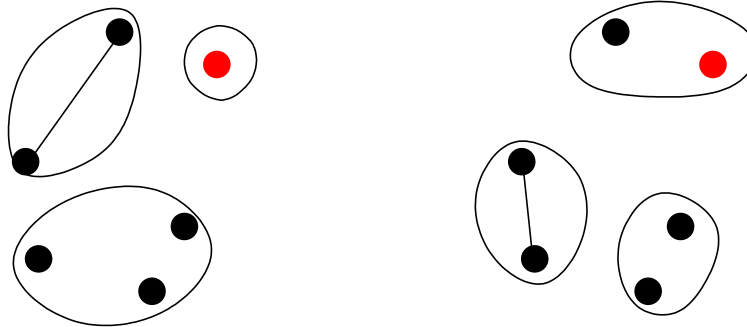


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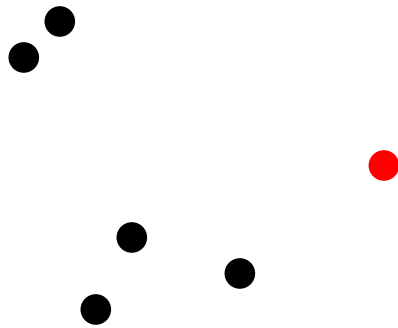


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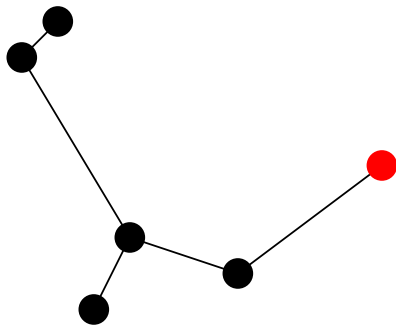


• is 2-interior

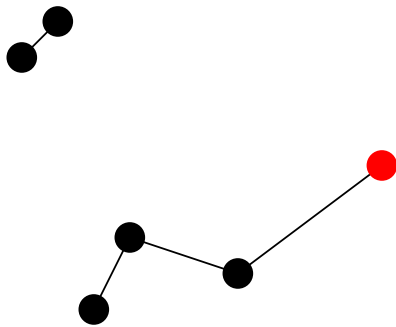
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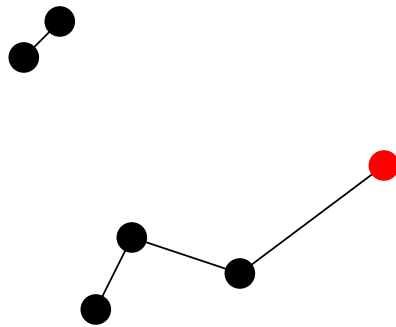
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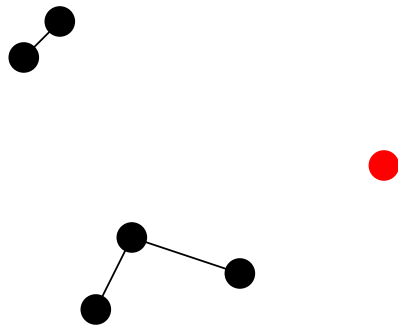


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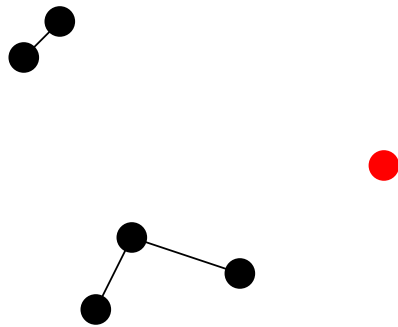
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● is 1-interior but not 2-interior

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the *interiority* degree of \bar{x} is

$d_{\bar{x}}$ = the largest k such that \bar{x} is k -interior

interiority degree

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interiority degree

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this combinatorial concept of interiority...

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this combinatorial concept of interiority...

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defines, for each aggregation criterion, a particular partition of the entity space into a finite number of iso-interiority regions

this combinatorial concept of interiority...

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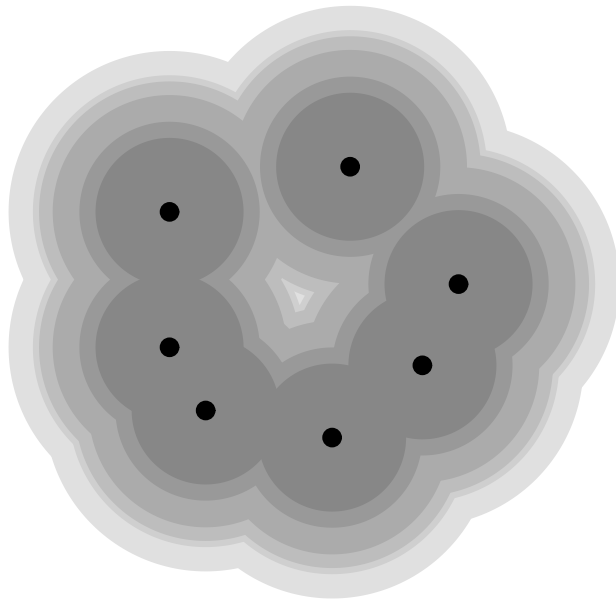
$$d : \mathcal{E} \setminus X \rightarrow \{0, 1, \dots, |X| - 1\}$$

this combinatorial concept of interiority...

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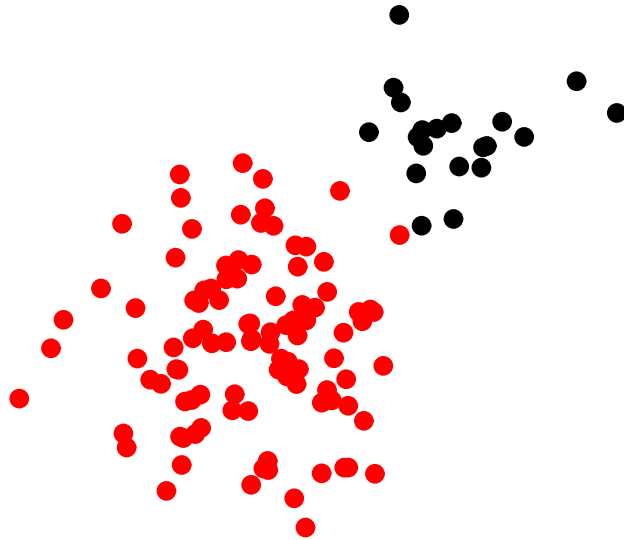
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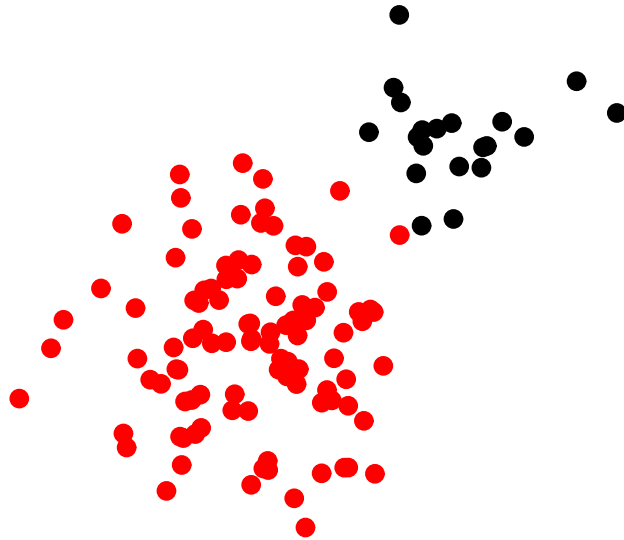
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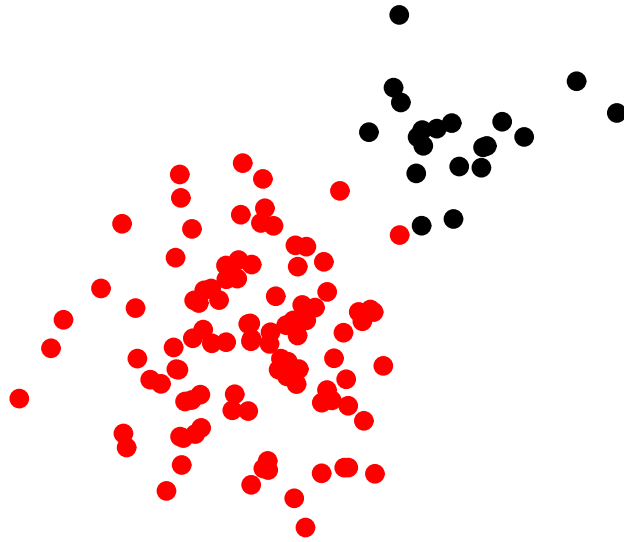
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$$D_{\bar{X}} = \{d(\bar{x}) : \bar{x} \in \bar{X} = \{\bullet\}\} \quad \text{interiority of } \bar{X}$$

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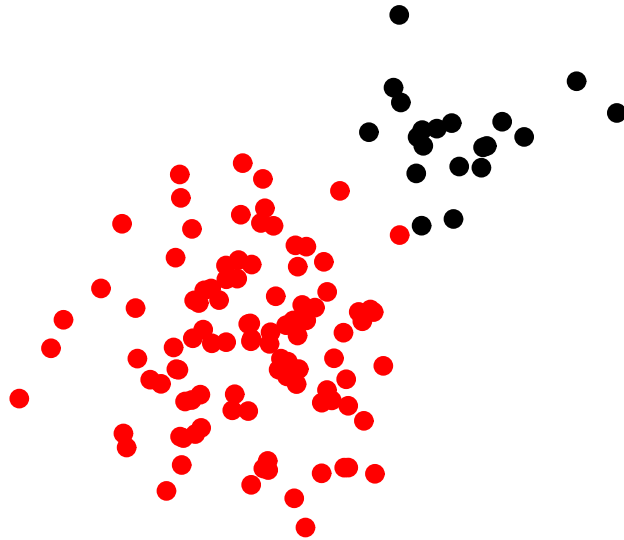


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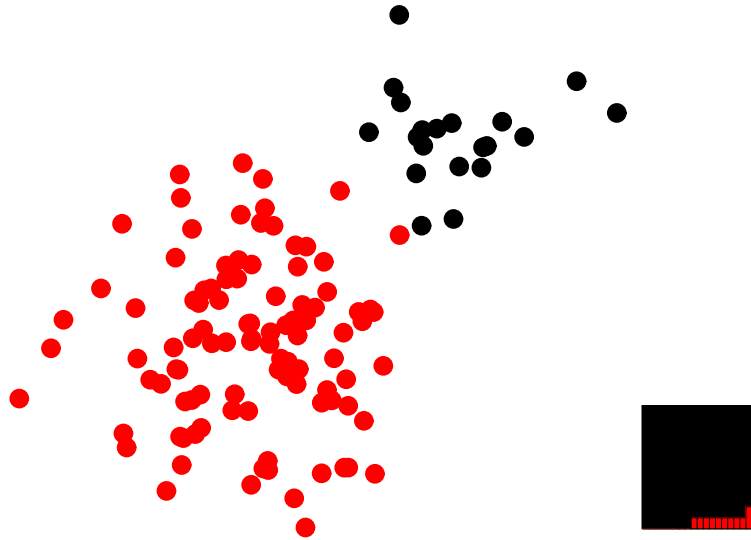
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DSI of m points with interiority degree $n = DSI$ of n points with interiority degree m

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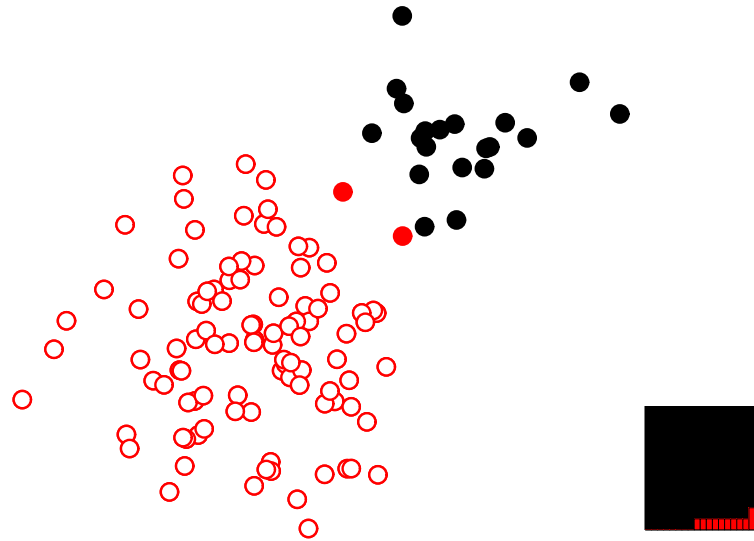


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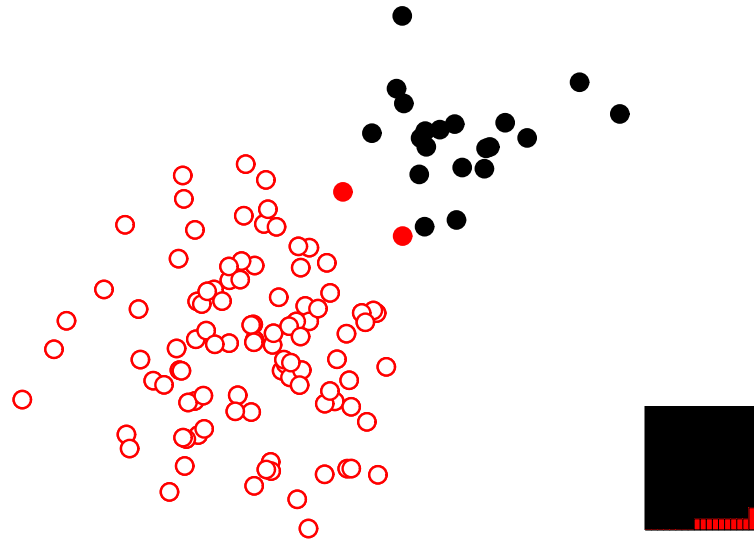


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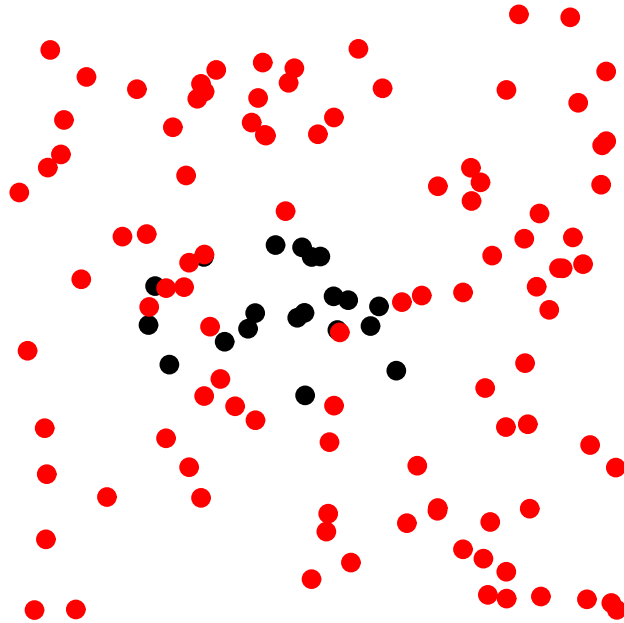
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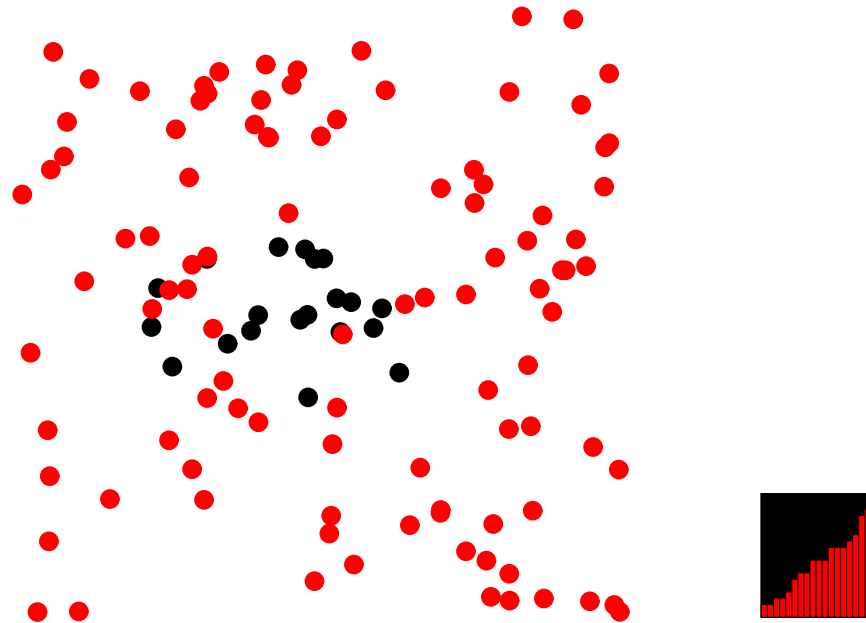
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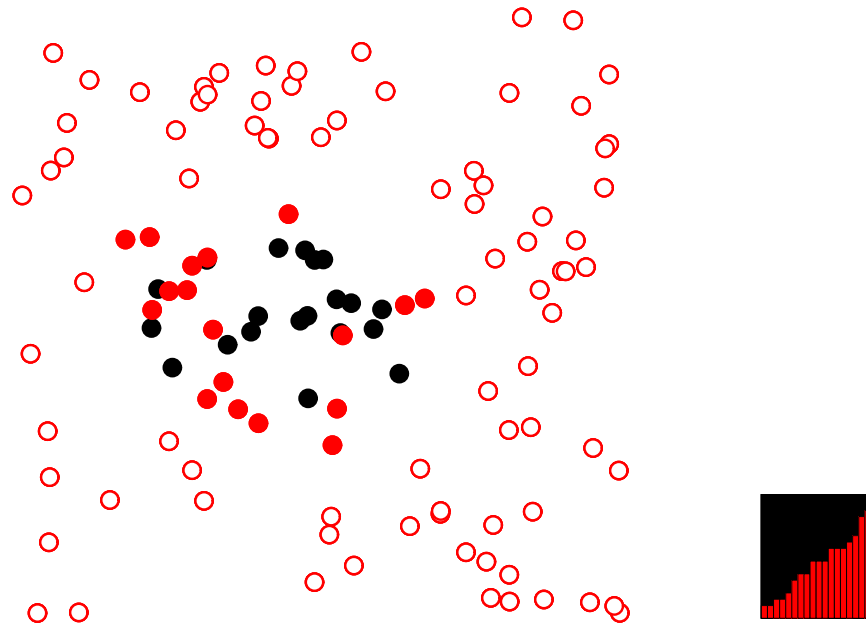
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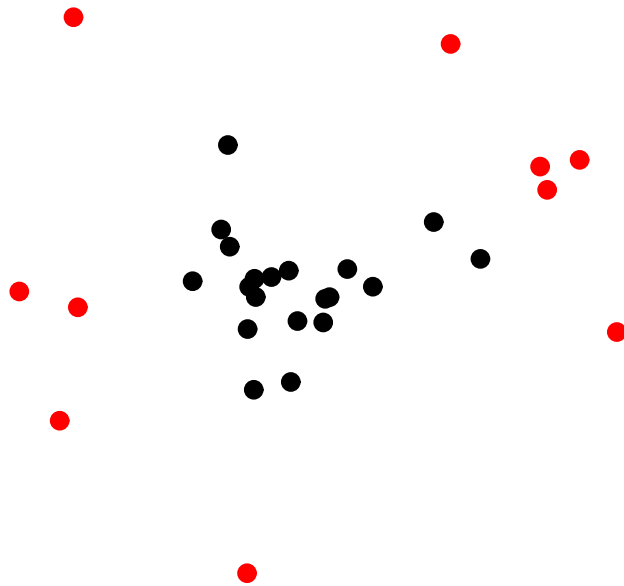
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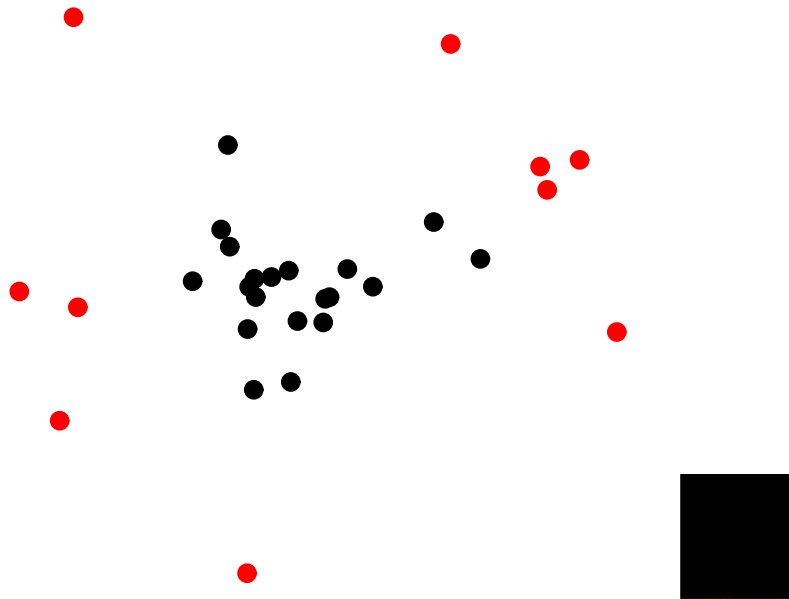
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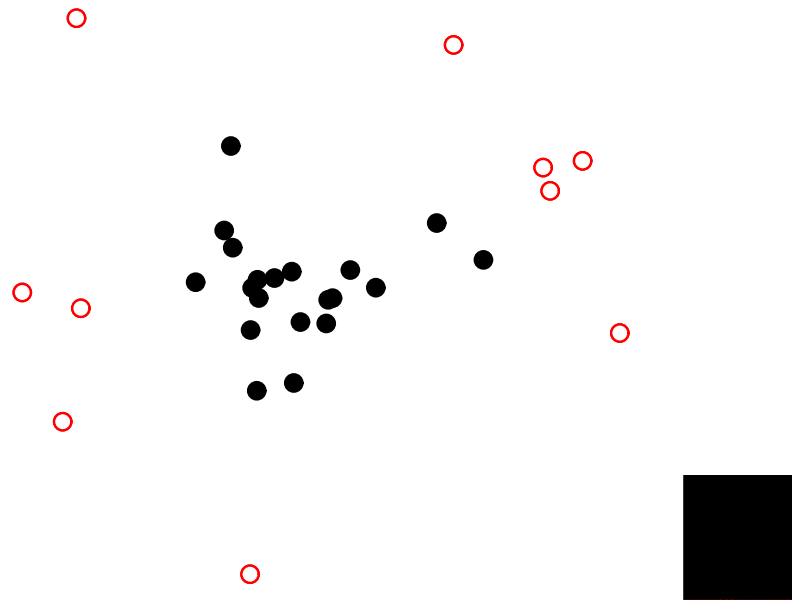
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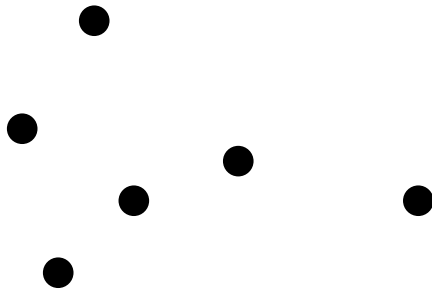
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a k -partition is adequate if it includes $k - 1$ singletons that are not in the interior of the convex hull of the remaining points

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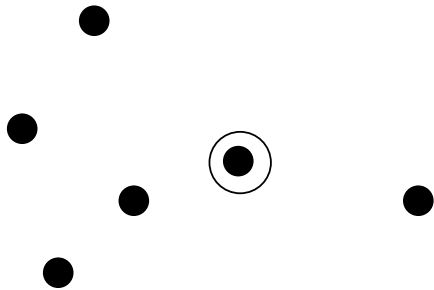
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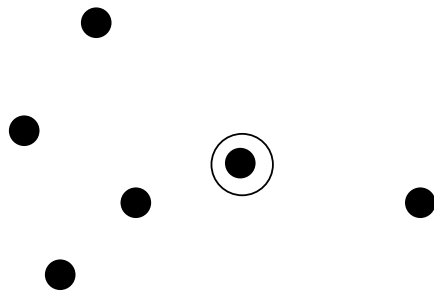
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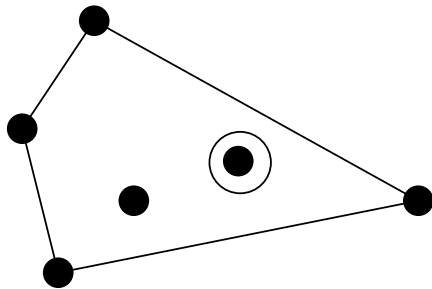


not adequate

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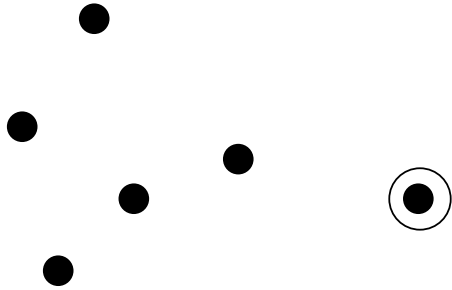


not adequate

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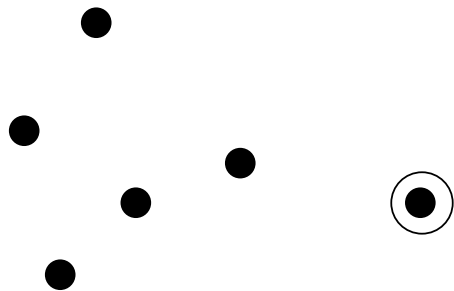
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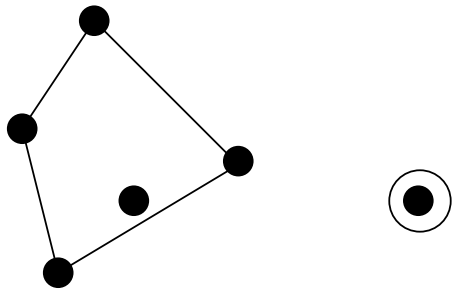


adequate

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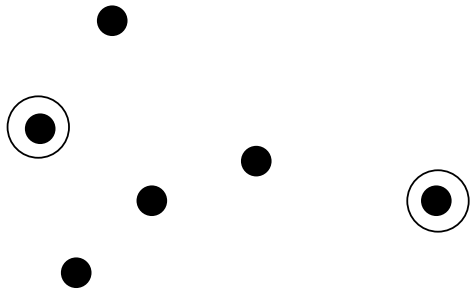


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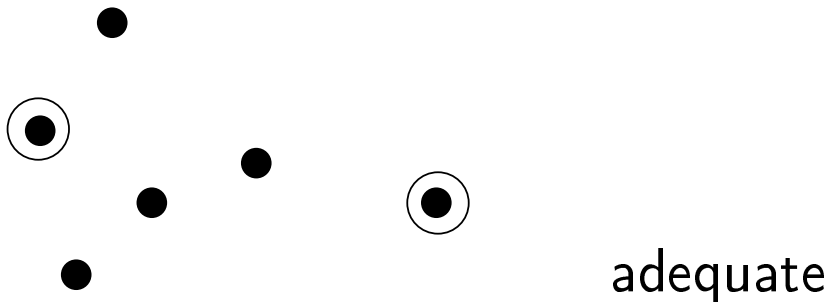
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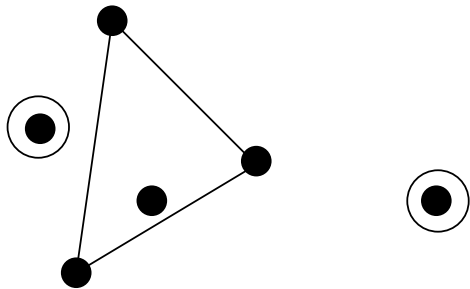
a k -partition is adequate if it includes $k - 1$ singletons that are not in the interior of the convex hull of the remaining points



convexity criterion

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adequate

convexity criterion

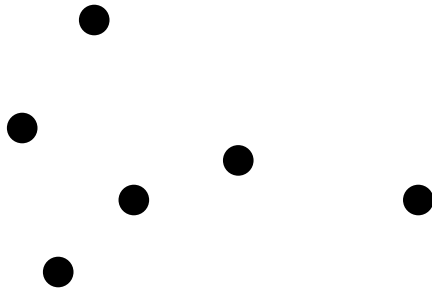
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\bar{x} is k -interior if it is inside the convex hull of any $|X| - k + 1$ points of X

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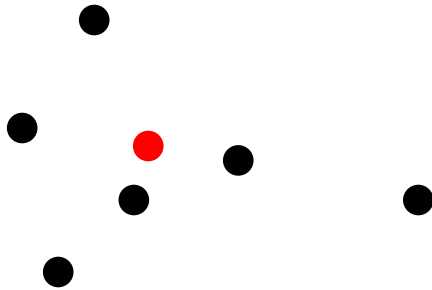
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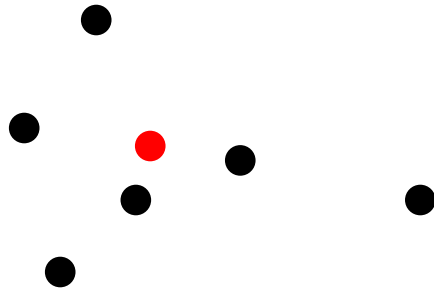
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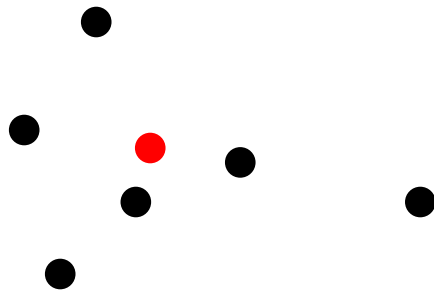


• is 1-interior

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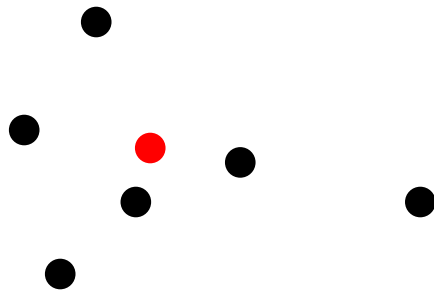


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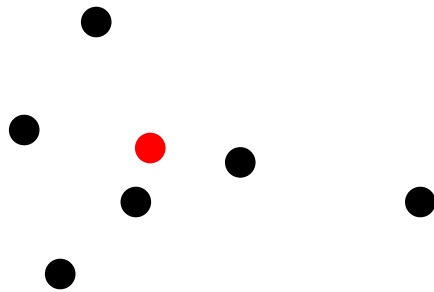
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$d(\bullet)$ is the minimum number of points to be removed from X such that \bullet is outside conv. hull of the remaining points

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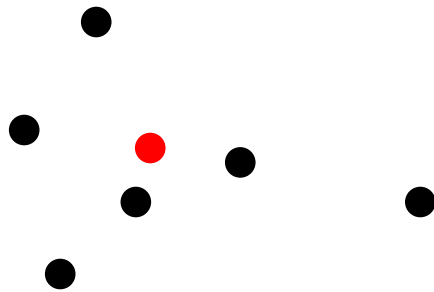
$d(\bullet)$ is the minimum number of points to be removed from X such that \bullet is outside conv. hull of the remaining points

$$d(\bullet) = 2$$

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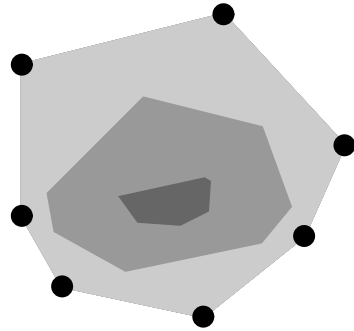
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$$d(\bullet) = 2$$

$d(\)$ - (*halfspace, location, Tukey*) depth

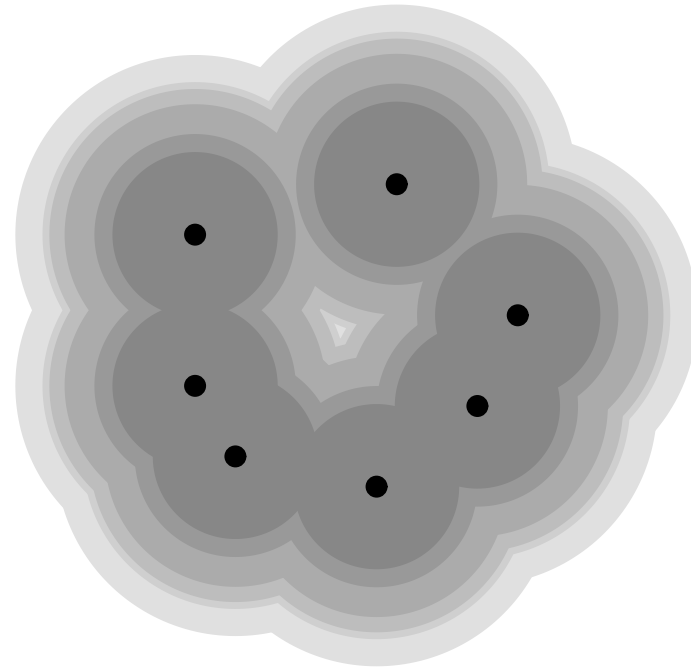
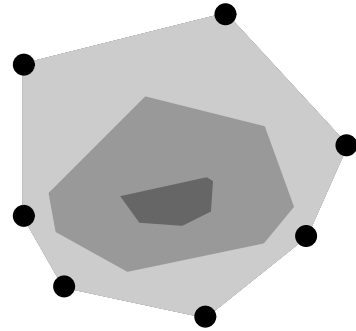
iso-interiority regions

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iso-interiority regions

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depth \hookrightarrow auto-interiority

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depth \hookrightarrow auto-interiority

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for $x \in X$, $d(x)$ is the minimum number of points to be removed from X such that x is outside the conv.hull of the remaining points

depth \hookrightarrow auto-interiority

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for $x \in X$, $d(x)$ is the minimum number of points to be removed from X such that x is outside the conv.hull of the remaining points

$d(x) = 1$ iff x is a vertex of the conv.hull(X)

depth \hookrightarrow auto-interiority

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depth \hookrightarrow auto-interiority

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depth \hookrightarrow auto-interiority

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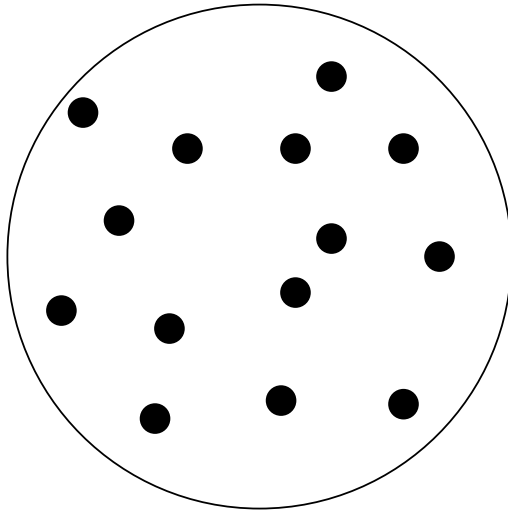
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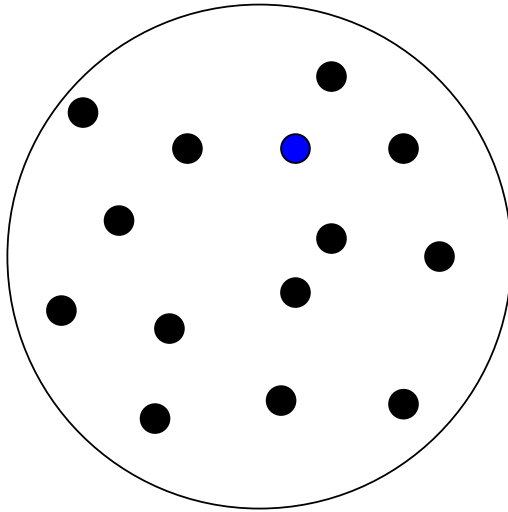
if X is uniformly distributed on an n -ball

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if X is uniformly distributed on an n -ball

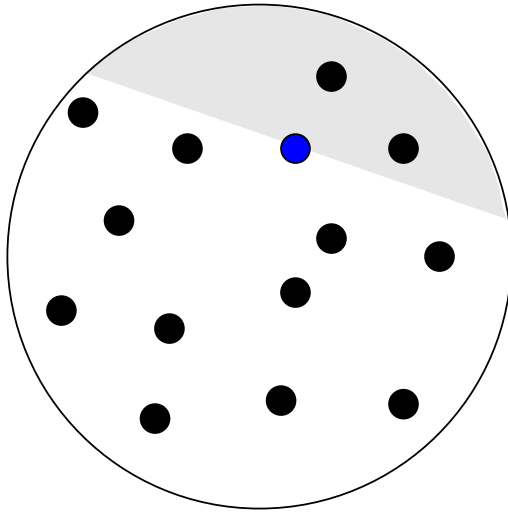
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$$\frac{d(\mathcal{x})}{|X|} \rightsquigarrow$$

if X is uniformly distributed on an n -ball

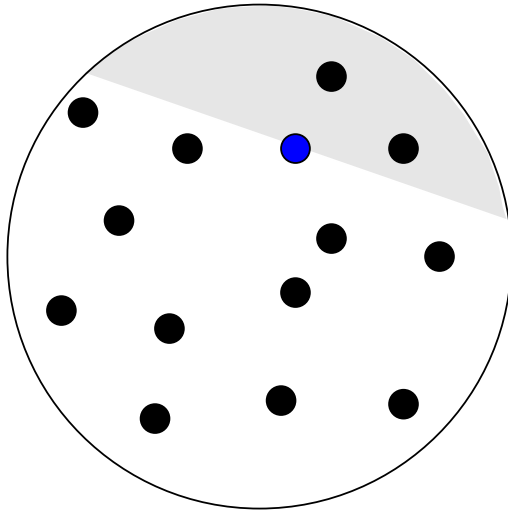
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$$\frac{d(\mathbf{x})}{|X|} \rightsquigarrow \frac{\text{vol}(\text{shaded region})}{\text{vol}(B_n)} = V_r(\mathbf{x})$$

if X is uniformly distributed on an n -ball

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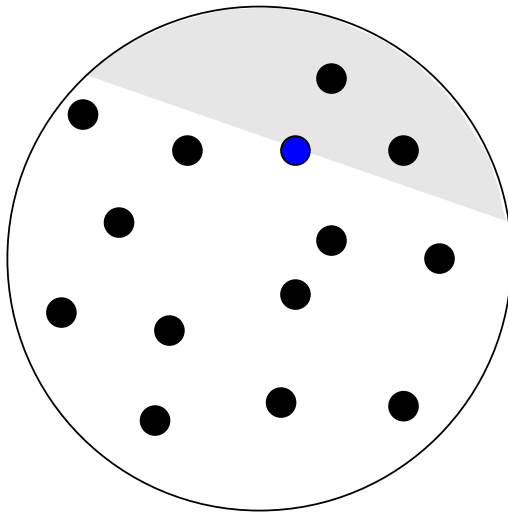


$$\frac{d(\mathbf{x})}{|X|} \rightsquigarrow \frac{\text{vol}(\text{shaded region})}{\text{vol}(B_n)} = V_r(\mathbf{x})$$

$$E[V_r(x)] = \int_{B_n} \frac{V_r(x)}{\text{vol}(B_n)} dx$$

if X is uniformly distributed on an n -ball

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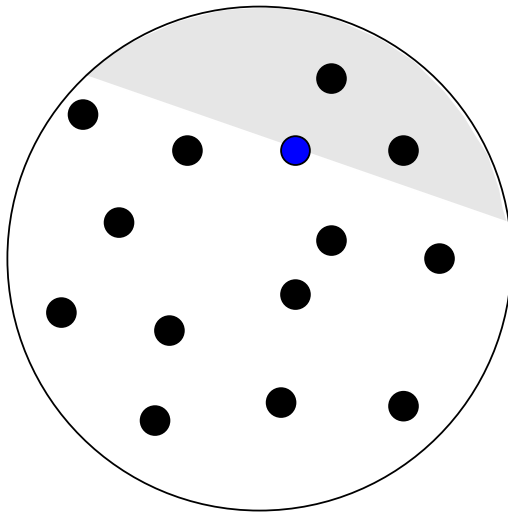


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$$E[V_r(x)] = \int_{B_n} \frac{V_r(x)}{\text{vol}(B_n)} dx = \frac{1}{2^{n+1}}$$

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Result holds if X is uniformly distributed on the closed region of \mathbb{R}^n delimited by an ellipsoid

if X is uniformly distributed on an n -ball

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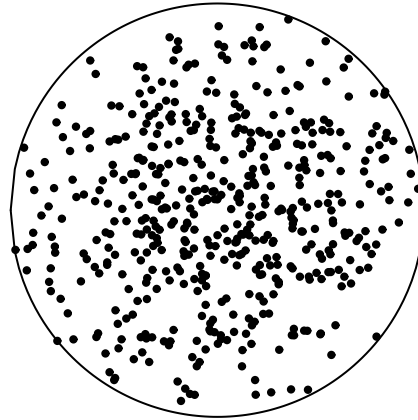
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$$E[V_r(x)] = \frac{1}{2^{n+1}} \implies \frac{1}{|X|} \sum_x V_r(x) \approx \frac{1}{2^{n+1}}$$

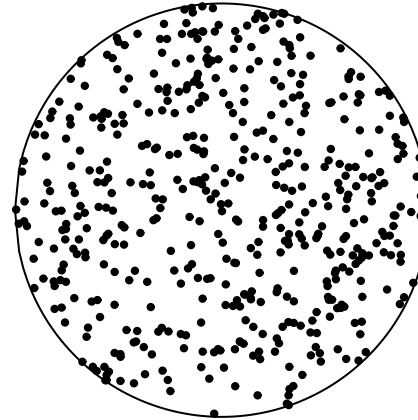
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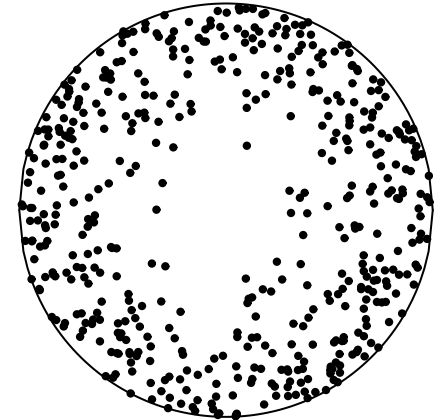
(a)

normal



(b)

uniform

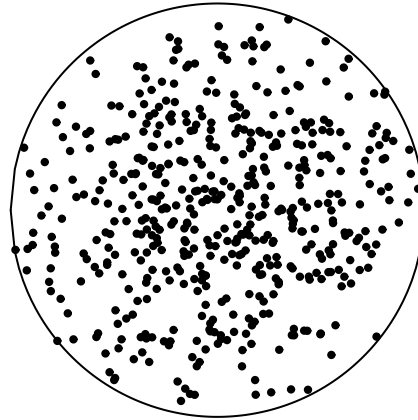


(c)

LDI

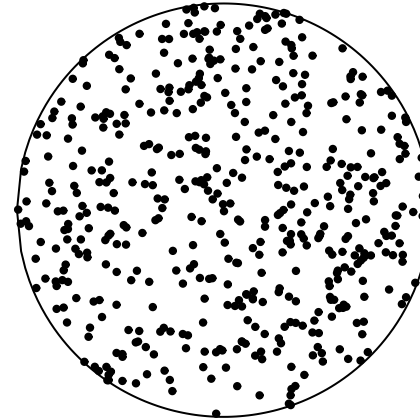
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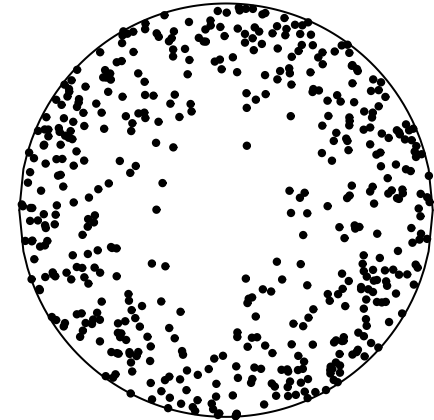
(a)

normal



(b)

uniform



(c)

LDI

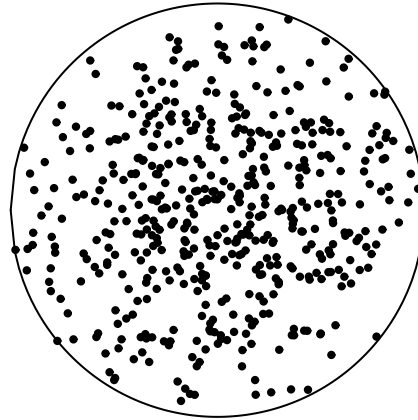
$$\frac{1}{|X|} \sum_x V_r(x) \quad 0.1874$$

$$0.1247$$

$$0.0582$$

if X is uniformly distributed on an n -ball

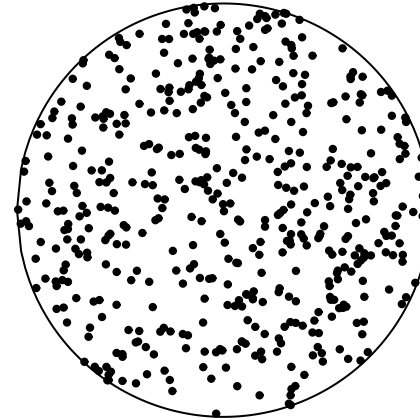
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(a)

normal

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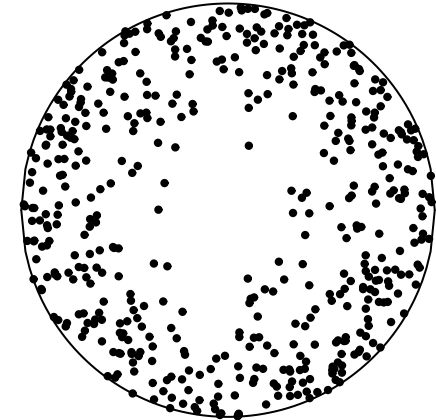


(b)

uniform

$$0.1247$$

$$E[V_r(x)] = \frac{1}{2^{n+1}} = \frac{1}{2^3} = 0.125$$



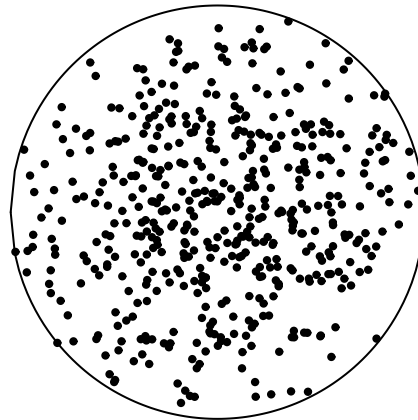
(c)

LDI

$$0.0582$$

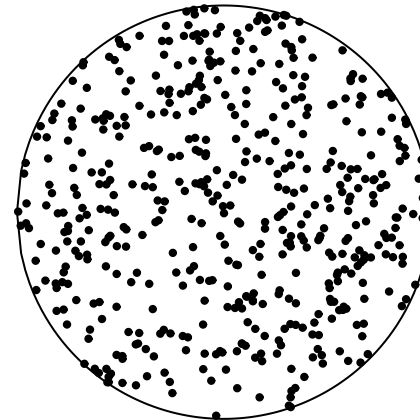
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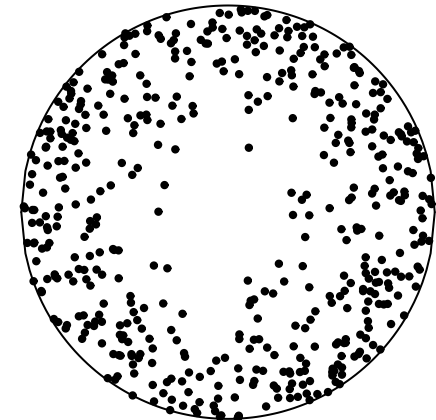
(a)

normal



(b)

uniform



(c)

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$$\frac{1}{|X|} \sum_x V_r(x) \quad 0.1874$$

$$0.1247$$

$$0.0582$$

$$E[V_r(x)] = \frac{1}{2^{n+1}} = \frac{1}{2^3} = 0.125$$

even for small $|X|$, $\frac{1}{|X|} \sum_x V_r(x) \approx E[V_r(x)] = \frac{1}{2^{n+1}}$, for uniformly distributed X