Boundary value problems for the infinity Laplacian: regularity and geometric results

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based on joint works with Graziano Crasta, Roma "La Sapienza"

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Initial motivation

Study the overdetermined boundary value problems

$$\begin{cases} -\Delta_{\infty} u = 1 & \text{in } \Omega \\ u = 0 & \text{on } \partial \Omega \\ |\nabla u| = c & \text{on } \partial \Omega \end{cases} \qquad \qquad \begin{cases} -\Delta_{\infty}^{N} u = 1 & \text{in } \Omega \\ u = 0 & \text{on } \partial \Omega \\ |\nabla u| = c & \text{on } \partial \Omega. \end{cases}$$

$$\label{eq:Laplacian} \begin{split} \Delta_{\infty} &= \text{infinity Laplacian} \\ \Delta_{\infty}^{\textit{N}} &= \text{normalized infinity Laplacian} \end{split}$$

Symmetry results

The overdetermined boundary value problem

$$\left\{ \begin{array}{ll} -\Delta u = 1 & \quad \mbox{in } \Omega, \\ u = 0 & \quad \mbox{on } \partial \Omega, \\ |\nabla u| = c & \quad \mbox{on } \partial \Omega, \end{array} \right.$$

admits a solution $\Longleftrightarrow \Omega$ is a ball.

[Serrin 1971]

Serrin's result extends to the case of the *p*-Laplacian operator, and of more general elliptic operators in divergence form [Garofalo-Lewis 1989, Damascelli-Pacella 2000, Brock-Henrot 2002, F.-Gazzola-Kawohl 2006] What happens for $p = +\infty$?

Symmetry breaking may occur!

This intriguing discovery leads to study a number of

geometric and regularity matters

Outline

- I. Background: overview on infinity Laplacian and viscosity solutions
- II. Overdetermined problem: a simple case (web functions)
- III. Geometric intermezzo
- IV. Regularity results for the Dirichlet problem
- V. Overdetermined problem: the general case

The infinity Laplace operator

$$\Delta_{\infty} u := \langle \nabla^2 u \cdot \nabla u, \nabla u \rangle \qquad \text{for all } u \in C^2(\Omega)$$

Where the name comes from:

Formally, it is the limit as $p \rightarrow +\infty$ of the *p*-Laplacian.

$$\Delta_{p} u = |\nabla u|^{p-2} \Delta u + (p-2) |\nabla u|^{p-4} \Delta_{\infty} u$$

If divide the equation $\Delta_p u = 0$ by $(p-2)|
abla u|^{p-4}$, we obtain

$$0=\frac{|\nabla u|^2}{p-2}\Delta u+\Delta_{\infty}u.$$

As $p \to +\infty$, we formally get $\Delta_{\infty} u = 0$.

A quick overview

 Origin: [Aronsson 1967] discovered the operator and found the "singular" solution

$$u(x,y) = x^{4/3} - y^{4/3} , \qquad \Delta_{\infty} u = 0 \text{ in } \mathbb{R}^2 \setminus \{axes\}.$$

Viscosity solutions: [Bhattacharya, DiBenedetto, Manfredi 1989], [Jensen 1998] proved the existence and uniqueness of a viscosity solution to

$$\begin{cases} \Delta_{\infty} u = 0 & \text{ in } \Omega \\ u = g & \text{ on } \partial \Omega \end{cases}$$

Optimization of Lipschitz extension of functions: $u \in AML(g)$, i.e.

 $u=g \text{ on } \partial\Omega \text{ and } \forall A\subset\subset\Omega, \ \forall v=u \text{ on } \partial A, \ \|\nabla u\|_{L^{\infty}(A)}\leq \|\nabla v\|_{L^{\infty}(A)}$

▷ Calculus of Variations in L[∞] [Juutinen 1998, Barron 1999, Crandall-Evans-Gariepy 2001, Crandall 2005, Barron-Jensen-Wang 2001]

- ▷ Regularity of ∞-harmonic functions
 - $C^{1,\alpha}$ for n = 2 [Savin 2005, Evans-Savin 2008]
 - differentiability in any space dimension [Evans-Smart 2011]

Remark: C^1 regularity in dimension n > 2 is a major open problem!

Inhomogeneous problems

$$\begin{cases} -\Delta_{\infty} u = 1 & \text{in } \Omega \\ u = 0 & \text{on } \partial \Omega \end{cases}$$

- existence and uniqueness of a viscosity solution u [Lu-Wang 2008]

- u is everywhere differentiable [Lindgren 2014]

Recent trend: study problems involving the normalized infinity Laplacian, in connection with "Tug-of-War differential games"

$$\Delta_{\infty}^{N} u := \begin{cases} \langle \nabla^{2} u \cdot \frac{\nabla u}{|\nabla u|}, \frac{\nabla u}{|\nabla u|} \rangle & \text{if } \nabla u \neq 0 \\ \\ [\lambda_{min}(\nabla^{2} u), \lambda_{max}(\nabla^{2} u)] & \text{if } \nabla u = 0 \end{cases} \text{ for all } u \in C^{2}(\Omega).$$

Existence and uniqueness of a viscosity solution have been proved for

$$\begin{cases} -\Delta_{\infty}^{N} u = 1 & \text{in } \Omega \\ u = 0 & \text{on } \partial \Omega \end{cases}$$

[Peres-Schramm-Sheffield-Wilson 2009, Lu-Wang 2010, Armstrong-Smart 2012]

Viscosity solutions

▷ A viscosity solution to $-\Delta_{\infty} u = 1$ in Ω is a function $u \in C(\Omega)$ which is both a viscosity sub-solution and a viscosity super-solution, meaning that, for all $x \in \Omega$ and for all smooth functions φ :

$$-\Delta_{\infty} \varphi(x) \leq 1$$
 if $u \prec_x \varphi$, $-\Delta_{\infty} \varphi(x) \geq 1$ if $\varphi \prec_x u$

 \triangleright For solutions to $-\Delta_{\infty}^{N} u = 1$ the above inequalities must be replaced by

$$\begin{cases} -\frac{\Delta_{\infty} \varphi(x)}{|\nabla \varphi(x)|^2} \leq 1 & \text{if } \nabla \varphi(x) \neq 0 \\ -\lambda_{\max}(\nabla^2 \varphi(x)) \leq 1 & \text{if } \nabla \varphi(x) = 0 \end{cases} \quad \begin{cases} -\frac{\Delta_{\infty} \varphi(x)}{|\nabla \varphi(x)|^2} \geq 1 & \text{if } \nabla \varphi(x) \neq 0 \\ -\lambda_{\min}(\nabla^2 \varphi(x)) \geq 1 & \text{if } \nabla \varphi(x) = 0. \end{cases}$$

[Crandall-Ishii-Lions 1992]

Simplified version of the overdetermined problem

Q. For which domains Ω is it true that the unique solution u to

$$(D) \quad \begin{cases} -\Delta_{\infty} u = 1 & \text{in } \Omega \\ u = 0 & \text{on } \partial \Omega \end{cases}$$

is of the form

$$u(x) = \varphi(d_{\Omega}(x))$$
 in Ω ?

We call such a function *u* a *web-function*.

Remark: u web $\Rightarrow |\nabla u| = |\varphi'(0)| = c$ on $\partial \Omega$.

Basic example: web solution on the ball

Look for a radial solution to problem (D) in a ball $B_R(0)$:

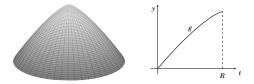
$$\begin{cases} -\Delta_{\infty} u = 1 & \text{in } B_R, \\ u = 0 & \text{on } \partial B_R. \end{cases}$$

If $u(x) = \varphi(R - |x|)$, we have to solve the 1D problem

$$-\varphi''(R-|x|)[\varphi'(R-|x|)]^2 = 1, \qquad \varphi(0) = 0, \qquad \varphi'(R) = 0.$$

The solution is

 $f(t) = c_0[R^{4/3} - (R-t)^{4/3}], \quad c_0 = 3^{4/3}/4 \qquad (\Rightarrow u \in C^{1,1/3}(B_R))$



Similar computations in the normalized case, with profile

$$g(t) = \frac{1}{2}[R^2 - (R - t)^2] \qquad (\Rightarrow u \in C^{1,1}(B_R))$$

Heuristics

Assume that u is a C^2 solution to problem (D) in a domain Ω .

 $\begin{array}{l} \mbox{Gradient flow (characteristics)} \\ \gamma(0) = x \end{array} \begin{cases} \dot{\gamma}(t) = \nabla u((\gamma(t))) \\ \gamma(0) = x \end{cases}$

P-function
$$P(x) := \frac{|\nabla u(x)|^4}{4} + u(x)$$

$$\frac{d}{dt}P(\gamma(t)) = |\nabla u|^2 \langle \nabla^2 u \cdot \nabla u, \nabla u \rangle + |\nabla u|^2 = |\nabla u|^2 (\Delta_{\infty} u + 1) = 0 \Rightarrow$$

 $\Rightarrow P(\gamma(t)) = \lambda$ (P is constant along characteristics)

 $\Rightarrow u(\gamma(t))$ can be explicitly determined by solving an ODE

Unfortunately from this information we cannot reconstruct u because we do not know the geometry of characteristics! ... BUT, if $u = \varphi(d_{\Omega})$:

- $\triangleright \nabla u$ is parallel to $\nabla d_{\Omega} \Rightarrow$ characteristics are line segments normal to $\partial \Omega$
- \triangleright By solving an ODE for φ as in the radial case, we get:

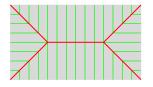
$$arphi(t)=f(t):=c_0\left[R^{4/3}-(R-t)^{4/3}
ight]$$
 ($R=$ length of the characteristic)

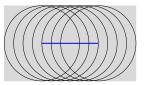
 \triangleright If we ask *u* to be differentiable, all characteristics must have the same length equal to the inradius ρ_{Ω} and *u* is given by

$$u(x) = \Phi_{\Omega}(x) := c_0 \left[\rho_{\Omega}^{4/3} - (\rho_{\Omega} - d_{\Omega}(x))^{4/3} \right].$$

When do characteristics have the same length?

▶ False in general





 $\label{eq:star} \begin{array}{l} \triangleright \ \ {\rm True} \iff \overline{\Sigma}(\Omega) = M(\Omega), \ {\rm where} \\ \hline \\ Cut \ locus \quad \overline{\Sigma}(\Omega) := \ {\rm the \ closure \ of \ the \ singular \ set} \ \Sigma(\Omega) \ {\rm of} \ d_\Omega \\ \hline \\ High \ ridge \quad M(\Omega) := \ {\rm the \ set} \ {\rm where} \ d_\Omega(x) = \rho_\Omega \end{array}$



Theorem (web-viscosity solutions)

The unique viscosity solution to problem

$$(D) \qquad \begin{cases} -\Delta_{\infty} u = 1 & \text{in } \Omega, \\ u = 0 & \text{on } \partial \Omega \end{cases}$$

is a web-function if and only if $M(\Omega) = \overline{\Sigma}(\Omega)$. In this case,

$$u(x) = \Phi_{\Omega}(x) := c_0 \left[\rho_{\Omega}^{4/3} - (\rho_{\Omega} - d_{\Omega}(x))^{4/3} \right]$$

- ▷ For the *normalized operator* Δ_{∞}^{N} , an analogous result holds true, with Φ_{Ω} replaced by $\Psi_{\Omega}(x) := \frac{1}{2} [\rho_{\Omega}^{2} - (\rho_{\Omega} - d_{\Omega}(x))^{2}].$
- ▷ In the regular case (C¹ solutions, C² domains) the result was previously obtained by Buttazzo-Kawohl 2011.
- \triangleright *Proof:* we use viscosity methods + non-smooth analysis results (in particular, a new estimate of d_{Ω} near singular points).

Singular sets of d_{Ω}

Let $\Omega \subset \mathbb{R}^n$ be an open bounded domain.

$$M(\Omega) \subseteq \Sigma(\Omega) \subseteq C(\Omega) \subseteq \overline{\Sigma}(\Omega)$$
.

 \triangleright $M(\Omega)$:= the high ridge of Ω

is the set where d_{Ω} attains its maximum over $\overline{\Omega}$;

 $\triangleright \ \Sigma(\Omega) := \textit{the skeleton of } \Omega$

is the set of points with multiple projections on $\partial \Omega$;

 $\triangleright \ C(\Omega):=$ the central set of Ω

is the set of the centers of all maximal balls contained into Ω ;

 $\,\triangleright\,\,\overline{\Sigma}(\Omega)\!:= \textit{the cut locus of }\Omega$

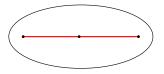
is the closure of $\Sigma(\Omega)$ in $\overline{\Omega}$.

In general the inclusions are strict

▷ when $\Omega = R$ is a rectangle, one has $M(R) \subsetneq \Sigma(R) = C(R) \subsetneq \overline{\Sigma}(R)$;



▷ when $\Omega = E$ is an ellipse, one has $M(E) \subsetneq \Sigma(E) \subsetneq C(E) = \overline{\Sigma}(E)$;



▷ more pathological examples:

$$\begin{split} &\Sigma(\Omega) \text{ is always } C^2\text{-rectifiable [Alberti 1994]} \\ &\overline{\Sigma}(\Omega) \text{ may have positive Lebesgue measure [Mantegazza-Mennucci 2003]} \\ &C(\Omega) \text{ may fail to be } \mathscr{H}^1\text{-rectifiable [Fremlin 1997]} \\ &\text{and may have Hausdorff dimension 2 [Bishop-Hakobyan 2008]} \end{split}$$

Which is the geometry of an open set Ω when $\overline{\Sigma}(\Omega) = M(\Omega)$?

Remark: If $\overline{\Sigma}(\Omega) = M(\Omega) =: S$, then

S is a closed set with empty interior and *positive reach*

Definition [Federer 1959]:

S has *positive reach* if, for every x in an open tubular neighborhood outside S, there is a unique minimizer of the distance function from x to S

 $\Leftrightarrow S \text{ is proximally } C^1 \text{, namely } \exists r_S > 0 : d_S \text{ is } C^1 \text{ on } \{0 < d_S(x) < r_S\}$ Similar definition for proximally C^2 sets.

Which is the geometry of a closed set S with empty interior and positive reach?

 \Rightarrow The set Ω will be a tubular neighborhood of S of radius ρ_{Ω} .

Theorem (Characterization of proximally C^1 sets with empty interior in \mathbb{R}^2) Let $S \subset \mathbb{R}^2$ be closed, with empty interior, proximally C^1 , and connected. Then S is either a singleton, or a 1-dimensional manifold of class $C^{1,1}$.



Proof: purely geometrical, hard to extend to higher dimensions...

Theorem (Characterization of proximally C^2 sets with empty interior in \mathbb{R}^2) Let $S \subset \mathbb{R}^2$ be closed, with empty interior, proximally C^2 , and connected. Then S is either a singleton, or a 1-dimensional manifold of class C^2 without boundary.



Theorem (Characterization of planar domains with $M(\Omega) = \overline{\Sigma}(\Omega)$) Let $\Omega \subset \mathbb{R}^2$ be an open bounded connected set with $M(\Omega) = \overline{\Sigma}(\Omega)$. Then:

- $\triangleright \Omega$ is either a disk or a parallel neighborhood of a 1-dim. $C^{1,1}$ manifold.
- ▷ If Ω is $C^2 \Rightarrow$ the case of manifold with boundary cannot occur.

 \triangleright If Ω is also simply connected $\Rightarrow \Omega$ is a disk.



Theorem (Extension to higher dimensions) Let $\Omega \subset \mathbb{R}^n$ be an open bounded *convex* set of class C^2 . If $M(\Omega) = \overline{\Sigma}(\Omega)$, then Ω is a ball.

In the web case:

We now know for which domains a web solution to the Dirichlet pb. exists.

In the general (non-web) case:

- > The geometry of characteristics is unknown.
- ▷ Even worse, we do not know if the gradient flow is well posed! $(\nabla u \text{ is in } L^{\infty}_{loc}(\Omega), \text{ NOT in } \text{Lip}_{loc}(\Omega).)$

However:

To have local forward uniqueness for the gradient flow, it is enough that u is *locally semiconcave* [Cannarsa-Yu 2009], i.e. $\exists C \ge 0$ s.t.

$$u(x+h)+u(x-h)-2u(x) \leq C|h|^2 \qquad \forall [x-h,x+h] \subset \Omega.$$

We need a *regularity result*!

Theorem (power-concavity of solutions)

Assume that Ω is convex, and let u be the unique viscosity solution to problem

$$D) \qquad \begin{cases} -\Delta_{\infty} u = 1 & \text{in } \Omega, \\ u = 0 & \text{on } \partial \Omega. \end{cases}$$

Then $u^{3/4}$ is concave in Ω .

- ▷ Counterpart of a well-known result for the *p*-Laplacian [Sakaguchi 1987]
- ▷ For the *normalized operator* Δ_{∞}^{N} , an analogous result holds true, with concavity exponent equal to 1/2.

Proof:

We adapt the convex envelope method [Alvarez-Lasry-Lions 1997].

The function $w := -u^{3/4}$ solves

$$\begin{cases} -\Delta_{\infty}w - \frac{1}{w} \left[\frac{1}{3}|\nabla w|^4 + \left(\frac{3}{4}\right)^3\right] = 0 & \text{in } \Omega\\ w = 0 & \text{on } \partial\Omega. \end{cases}$$

We show that w^{**} is a supersolution to the same problem.

By applying a comparison principle, we get $w^{**} \ge w$.

Hence $w = w^{**}$, i.e. w is convex.

Corollary (local semiconcavity and C^1 -regularity of solutions) Assume that Ω is convex, and let u be the unique viscosity solution to problem

$$(D) \qquad \begin{cases} -\Delta_{\infty} u = 1 & \text{in } \Omega, \\ u = 0 & \text{on } \partial \Omega. \end{cases}$$

Then u is locally semiconcave and continuously differentiable in Ω .

 \triangleright Same result for the *normalized operator* Δ_{∞}^{N} .

▷ The optimal expected regularity is of type $C^{1,\alpha}$. In the normalized case, we can prove that u is $C^{1,1} \Leftrightarrow M(\Omega) = \overline{\Sigma}(\Omega)$. Assuming Ω convex, characteristics are now back at our disposal!

Heuristics - continued

$$P(x) := \frac{|\nabla u|^4}{4} + u$$
, with u solution to (D)

 \triangleright Along characteristics: $\frac{d}{dt}(P(\gamma(t)) = 0 \Rightarrow P(\gamma(t))$ is constant

▷ Assuming
$$u = 0$$
 and $|\nabla u| = c$ on $\partial \Omega \Rightarrow P$ is constant on Ω .

 \triangleright If P is constant on $\Omega \Rightarrow u$ solves a first order HJ equation

$$\Rightarrow \text{ by uniqueness [Barles 1990]} u(x) = \Phi_{\Omega}(x) := c_0 \left[\rho_{\Omega}^{4/3} - (\rho_{\Omega} - d_{\Omega}(x))^{4/3} \right]$$

 \Rightarrow by the results in the web-case $M(\Omega) = \overline{\Sigma}(\Omega)$.

Lemma 1 (*P*-function inequalities) Assume Ω is convex. Then

$$\min_{\partial\Omega}\frac{|\nabla u|^4}{4} \leq P(x) \leq \max_{\overline{\Omega}} u \qquad \forall x \in \overline{\Omega}.$$

Proof:

The supremal convolutions

$$u^{\varepsilon}(x) = \sup_{y} \left\{ u(y) - \frac{|x-y|^2}{2\varepsilon} \right\}$$

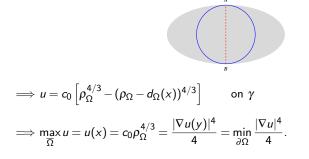
are of class $C^{1,1}$ and are *sub-solutions* of the PDE $\Rightarrow P_{\varepsilon} := \frac{|\nabla u^{\varepsilon}|^4}{4} + u^{\varepsilon}$ is increasing along the gradient flow of u^{ε} \Rightarrow in the limit as $\varepsilon \to 0$ we obtain the required inequalities. Lemma 2 (matching of upper and lower bounds) Assume Ω convex. If u satisfies the overdetermined condition $|\nabla u| = c$ on $\partial \Omega$, then

$$\frac{c^4}{4} = \min_{\partial \Omega} \frac{|\nabla u|^4}{4} = \max_{\overline{\Omega}} u.$$

Proof: Key remark: the web-function Φ_{Ω} is a *super-solution* to $-\Delta_{\infty}u = 1$

 $\implies \Phi_B \leq u \leq \Phi_\Omega$ on B = inner ball of radius ρ_Ω

 $\implies \Phi_B = u = \Phi_\Omega$ on $\gamma = [x, y]$, with $x \in M(\Omega)$, $y \in \partial \Omega$



Theorem (Serrin-type theorem for Δ_{∞} and Δ_{∞}^N) Assume that Ω is convex. Then each of the overdetermined problems

	$\int -\Delta_{\infty} u = 1$	in Ω	$\int -\Delta_{\infty}^{N} u = 1$	in Ω
{	<i>u</i> = 0	on $\partial \Omega$ <	<i>u</i> = 0	on $\partial \Omega$
	$ \nabla u = c$	on $\partial \Omega$	$ \nabla u = c$	on $\partial \Omega$

admits a solution $\iff M(\Omega) = \overline{\Sigma}(\Omega)$.

By the previous geometric results + convexity assumption:

- ▷ If $n = 2 \iff \Omega$ is a *stadium*.
- $\triangleright \text{ If } n = 2 \text{ and } \Omega \text{ is } C^2 \iff \Omega \text{ is a } ball.$

Link between symmetry breaking and boundary regularity!

Open problems

- $\triangleright\,$ Prove Serrin-type theorem for Δ_∞ or Δ^N_∞ without the convexity restriction.
- ▷ Characterize domains with $M(\Omega) = \overline{\Sigma}(\Omega)$ in higher dimensions.

▷ Study the regularity preserving properties of the parabolic flow governed by Δ_{∞} or Δ_{∞}^{N} .

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MANY THANKS FOR YOUR ATTENTION

and

HAPPY BIRTHDAY LUÍSA!

Ilaria Fragalà, Politecnico di Milano Boundary value problems for the infinity Laplacian