Explicit Formulas for Relaxed Disarrangement Densities from Structured Deformations

Marco Morandotti

joint with Ana C. Barroso (CMAF-UL), José Matias (IST-UL) and David R. Owen (CMU)

(SISSA, Trieste, Italy)

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hence the question: does $\mathcal{V}^{[\cdot]}$ have an associated disarrangement density? If so, how does it depend on (g,G)?

SISSA

Given an energy density of the form

$$E(u) := \int_{\Omega} W(\nabla u) \, \mathrm{d}\mathcal{L}^N + \int_{J(u) \cap \Omega} \psi([u], \nu) \, \mathrm{d}\mathcal{H}^{N-1},$$



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$$I(\boldsymbol{g}, \boldsymbol{G}) = \int_{\Omega} H(
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Image: A matrix

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The bulk density H and the surface density h are derived via a *cell formula*.



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Theorem (Owen-Paroni, 2015)

Given $\psi: \mathbb{R}^N \times \mathcal{S}^{N-1} \rightarrow [0, +\infty)$ such that

- there exists C > 0: $0 \leq \psi(\xi, \nu) \leq C|\xi|$,
- for all t > 0, $\psi(t\xi, \nu) = t\psi(\xi, \nu)$,
- for all ξ_1, ξ_2, ν , $\psi(\xi_1 + \xi_2, \nu) \leq \psi(\xi_1, \nu) + \psi(\xi_2, \nu)$,

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if we define, for any p > 1,

 $I(\boldsymbol{g},\boldsymbol{G}) := \inf \left\{ \liminf_{n \to \infty} \int_{J(u_n) \cap \Omega} \psi([u_n],\nu) \, \mathrm{d}\mathcal{H}^{N-1} : u_n \in \boldsymbol{SBV}(\Omega;\mathbb{R}^N) \right\}$

$$u_n \stackrel{L^1}{\to} \mathbf{g}, \ \nabla u_n \stackrel{*}{\to} \mathbf{G}, \ \sup_n (|\nabla u_n|_p + |Du_n|(\Omega)) < +\infty \bigg\},$$

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we have

$$I(\boldsymbol{g}, \boldsymbol{G}) = \int_{\Omega} H(
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Formulas for Disarrangement Densities

Theorem (Owen-Paroni, 2015)

The densities H and h are given by

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where
$$\begin{cases} 0 \quad \text{if } -1/2 < x : n < 0 \end{cases}$$

$$u_{\xi,\eta}(x) := egin{cases} 0 & ext{if} - 1/2 < x \cdot \eta < 0, \ \xi & ext{if} \ 0 \leqslant x \cdot \eta < 1/2. \end{cases}$$

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Explicit formulas

Theorem (Owen-Paroni (2015))

The choices $\psi^{|\cdot|}(\xi,\nu) := |\xi \cdot \nu|$ and $\psi^{\pm}(\xi,\nu) := (\xi \cdot \nu)^{\pm}$ yield

 $H^{[\cdot]}(\boldsymbol{A},\boldsymbol{B})=|\mathrm{tr}(\boldsymbol{A}-\boldsymbol{B})|,\qquad h^{[\cdot]}(\xi,\nu)=|\xi\cdot\nu|=\psi^{[\cdot]}(\xi,\nu),$

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Therefore, the functional for the minimal volume swept out by disarrangements reads

$$\mathcal{V}^{|\cdot|}(g,G;\mathcal{P}) = \int_{\mathcal{P}} \left| \operatorname{tr}(
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A crucial step in OP's proof was to show that

$$H^{|\cdot|}(A,B) \leqslant |\operatorname{tr}(A-B)|.$$



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Our contribution

Given $A, B \in \mathbb{R}^{N \times N}$, there holds

$$\begin{split} |\mathrm{tr}(\boldsymbol{A} - \boldsymbol{B})| \leqslant & \inf \left\{ \int_{J(u)} |[u] \cdot \nu| \, \mathrm{d}\mathcal{H}^{N-1} : u \in \boldsymbol{SBV}(\boldsymbol{Q}; \mathbb{R}^N) \\ u(x) = \boldsymbol{A}x \text{ on } \partial \boldsymbol{Q}, \ \nabla u \in \boldsymbol{L}^p(\boldsymbol{Q}), \ \int_{\boldsymbol{Q}} \nabla u = \boldsymbol{B} \right\} \end{split}$$



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Given $A, B \in \mathbb{R}^{N \times N}$, there holds

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We prove that



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• Matias' Lemma (2007): Given $\Omega \subset \mathbb{R}^N$ bounded open and $M \in \mathbb{R}^{N \times N}$, there exists C(N) > 0 and $u \in SBV(\Omega; \mathbb{R}^N)$:



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 $(1) \ u_{|\partial Q} = 0, (2) \ \nabla u = M \ \text{a.e.}, (3) \ |\underline{D}^s u|(\Omega) \leqslant C(N)||\underline{M}||\mathcal{L}^N(\Omega).$



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- Let $n \ge 1$ and define the frame $\mathcal{F}_n := Q \setminus (1 \frac{2}{n+2})Q$.



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- Let $n \ge 1$ and define the frame $\mathcal{F}_n := Q \setminus \overline{(1 \frac{2}{n+2})Q}$.
- Apply the Lemma to obtain $u^{(n)}: \mathcal{F}_n \to \mathbb{R}^N$: (1) $u^{(n)}_{|\partial \mathcal{F}_n} = 0$,



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- Let $\hat{M} := \frac{1}{2}(M + M^{\top})$ and choose a o.n. basis $\{e_i\}$: $\hat{M}e_i = \lambda_i e_i$.



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Theorem

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Thank you for your attention!

