

Comparison of constitutive laws for modeling high-temperature superconductors

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Motivation

- ▶ Numerical models routinely used to model electromagnetic response of superconductors
- ▶ Many numerical methods, codes and software available
- ▶ Inputs: geometry, boundary conditions, constraints,..., **material properties**
- ▶ Superconductors usually simulated with critical state or power-law models

Question

Are these simple choices OK for all practical cases?

We compare three models

1. Critical state model – CSM (1 parameter: J_c)

$$J = 0 \text{ or } J_c \text{ (thus } E \text{ is multi-valued)} \quad (1)$$

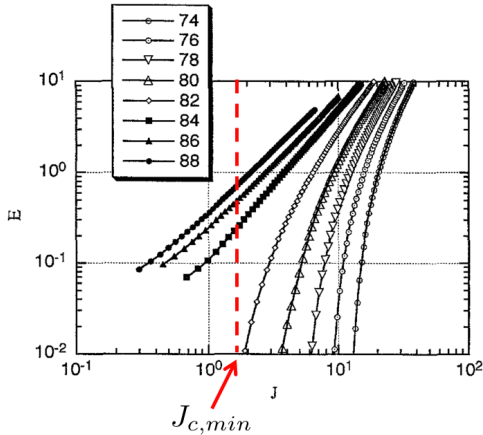
2. Power law model (2 parameters: J_c and n)

$$E = E_c \left(\frac{J}{J_c} \right)^n \quad (2)$$

3. Percolation model (3 parameters: J_c , $J_{c,\min}$ and n)

$$E = \begin{cases} 0 & \text{if } J \leq J_{c,\min} \\ E_c \left(\frac{J - J_{c,\min}}{J_c - J_{c,\min}} \right)^n = k (J_c - J_{c,\min})^n & \text{if } J > J_{c,\min} \end{cases} \quad (3)$$

Percolation model



Percolation model

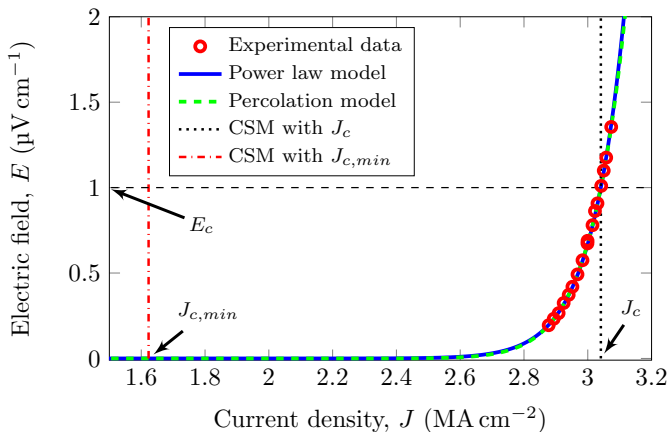
$$E = k (J_c - J_{c,min})^n$$

$$E = 0 \text{ if } J < J_{c,min}$$

True lossless behavior

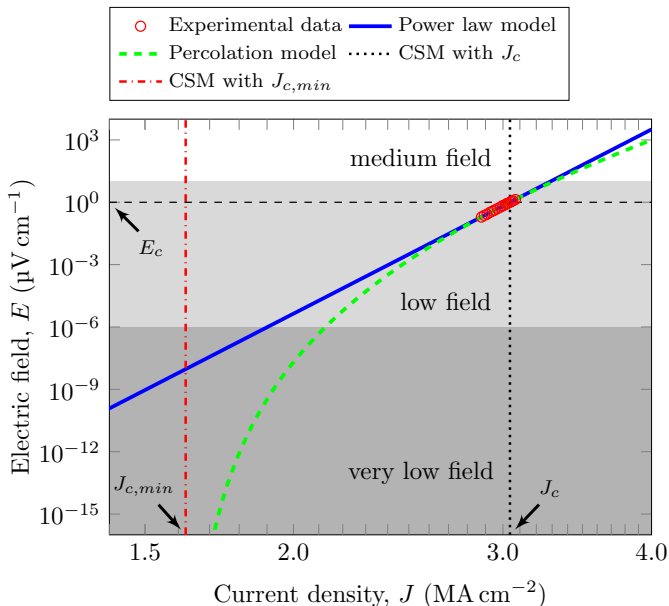
Source: Yamafuji and Kiss 1996 Physica C 258 197

One material, four models



(RE)BaCuO tape, 4 mm wide, characterized in self-field at 77 K

One material, four models



What determines the operating field range?

- ▶ The magnitude of the transport current (higher $J =$ higher E)
- ▶ The rate of variation of the magnetic field dB/dt (current ramp in a magnet, frequency of AC excitations)

Here we consider three scenarios

1. Magnetic relaxation in an HTS slab (DC operation)
2. AC transport current in a HTS strip (AC operation)
3. AC ripples in HTS strip carrying DC current (DC+AC operation)

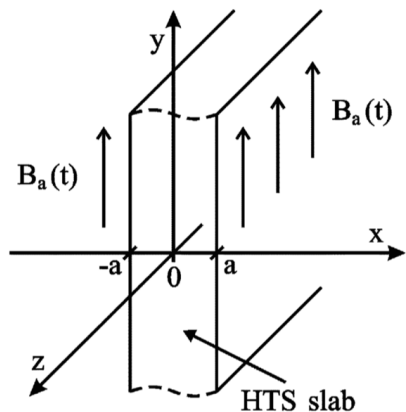
Material parameters and numerical methods

Model name	Parameter values and units
Power law model	$J_c = 3.041 \text{ MA cm}^{-2}$, $n = 29.44$, $E_c = 1 \text{ } \mu\text{V cm}^{-1}$ (not a fitting parameter)
Percolation model	$J_{c,\min} = 1.623 \text{ MA cm}^{-2}$, $n = 13.37$, $k = 0.0093775$
CSM with J_c	$J_c = 3.041 \text{ MA cm}^{-2}$
CSM with $J_{c,\min}$	$J_c = J_{c,\min} = 1.623 \text{ MA cm}^{-2}$

Employed numerical methods

- ▶ 1-D finite element model for slabs (COMSOL)
Sirois/Grilli, 2008 IEEE TAS **18** (3) 1733-1742
- ▶ 1-D integral method for thin strips (COMSOL)
Brambilla *et al* 2008 SuST **21** (10) 105008
- ▶ 2-D self-programmed code
Morandi/Fabbri 2015 SuST **28** (2) 024004

Case 1: slab in DC field



$$2a = 1 \mu\text{m}$$

$$B_p = \mu_0 J_c a = 19.1 \text{ mT}$$

$$B_a(t) = \begin{cases} 0 & \text{if } t < 0 \\ B_p/2 & \text{if } t \geq 0 \end{cases}$$

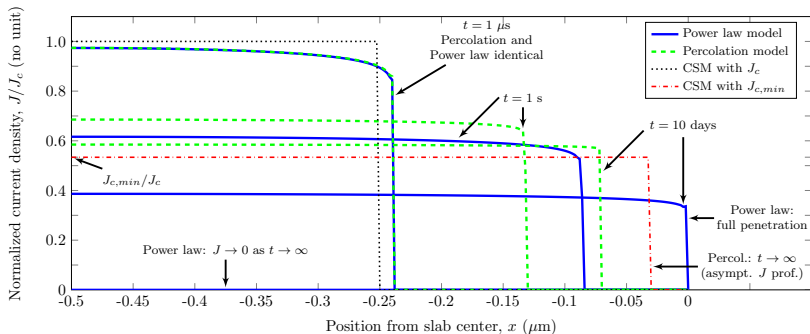
B_a turned on
"instantaneously" at $t = 0$

Numerically, the step function
is approximated by a 100 ns
ramp

Case 1: slab in DC field

Current density profiles between $1 \mu\text{s}$ and more than 10 days

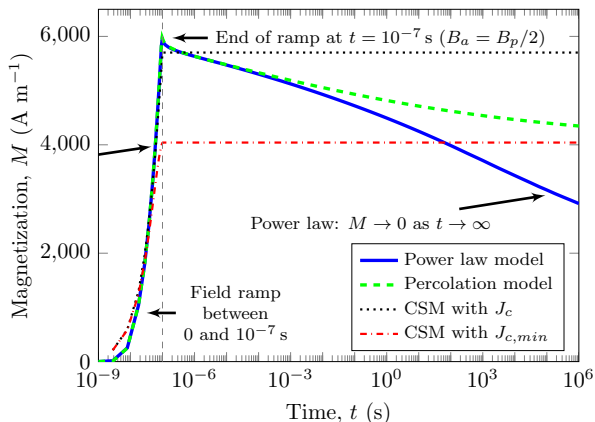
- ▶ PM relaxes more slowly than PL and converges to $\text{CSM}(J_{c,\min})$ as $t \rightarrow \infty$
- ▶ PL fully penetrates the samples after 303 s, and converges to 0 as $t \rightarrow \infty$



Case 1: slab in DC field

Magnetic moment vs. time

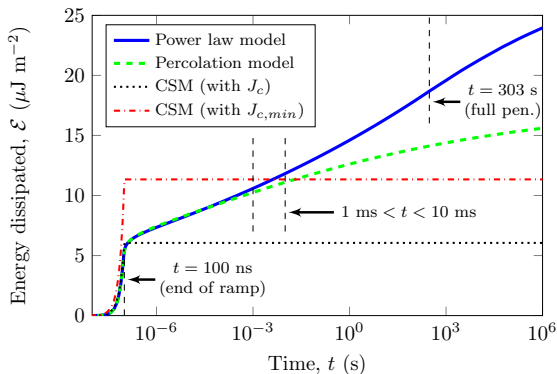
- ▶ PM converges asymptotically to $\text{CSM}(J_{c,\min})$ as $t \rightarrow \infty$
- ▶ PL results in complete loss of magnetization as $t \rightarrow \infty$
- ▶ $\text{CSM}(J_c)$ has no special significance in this case



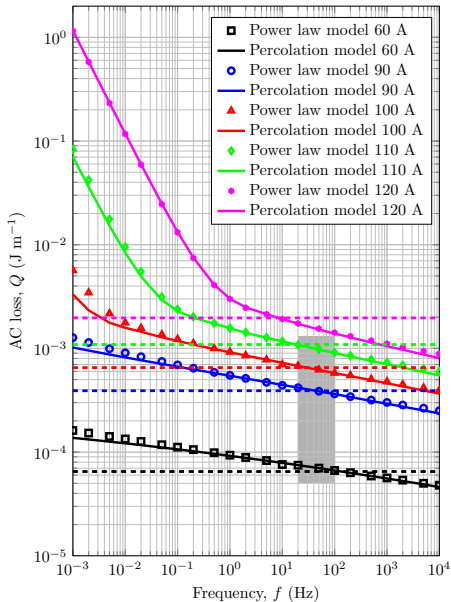
Case 1: slab in DC field

Accumulated energy loss vs. time

- ▶ CSM models do not account for relaxation losses
- ▶ Loss trends for PL and PM split after 10-20 ms (approx. time scale of AC power signals)



Case 2: thin strip with AC transport current

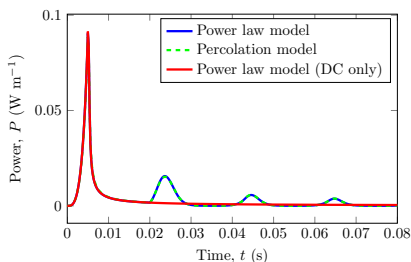
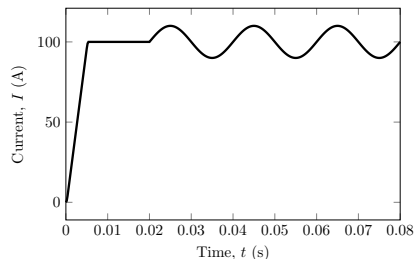


Shaded area:

frequency range where Norris's formula (dashed lines) agrees with percolation and power-law models

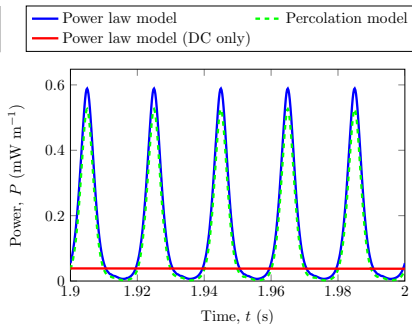
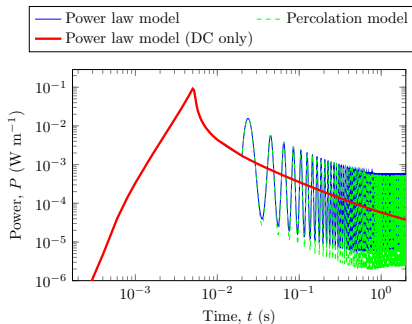
Case 3: thin strip with DC transport current + AC ripples

- ▶ Strip's critical current: 121.64 A
- ▶ DC current: 100 A ramped in 5 ms
- ▶ AC ripples: 10 A applied after waiting for 15 ms



Case 3: thin strip with DC transport current + AC ripples

- ▶ After 2 s, relaxation losses are still 25-30 % of the AC losses
- ▶ After 100 s, they are just 1 %
- ▶ On practical time scales (minutes to hours), only the losses associated to the AC component matter



Conclusion

- ▶ In DC cases (long time scales, very low electric field):
 - ▶ Only the percolation model can correctly predict the magnetic relaxation losses and the critical state profile
 - ▶ The CSM should be used with $J_c = J_{c,\min}$ to give physically relevant results
- ▶ With purely AC excitations:
 - ▶ Both percolation and power law models are suitable (10-20% difference in results, compatible with experimental accuracy)
 - ▶ The CSM predicts correct result only in a particular range of frequencies, which is coincidentally (?) that of power applications
 - ▶ Scaling laws relating the power-law and CSM as a function of frequency have been developed (Chen, Pardo), but only for particular geometries
- ▶ In the case of DC + AC ripples:
 - ▶ Same conclusions of purely AC cases apply (AC takes over)

More details in Sirois/Grilli/Morandi 2018 IEEE TAS (in press)
<https://doi.org/10.1109/TASC.2018.2848219>