

# Modeling high temperature superconducting magnetics with an open source finite element library

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6<sup>th</sup> International Workshop on Numerical Modeling of High  
Temperature Super Conductors

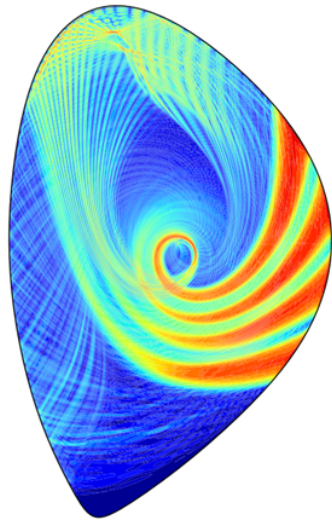
26-29 June 2018, Caparica-Portugal

# Commonwealth Fusion System (CFS)

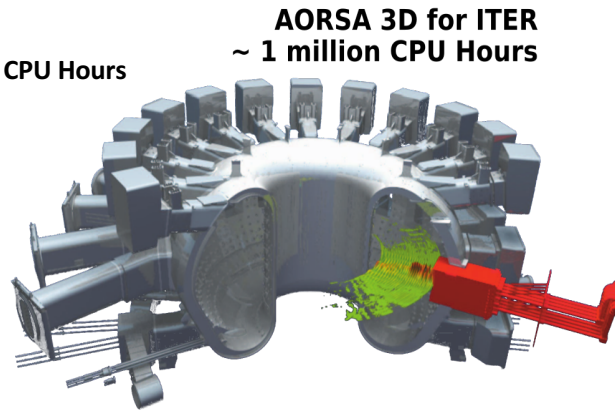
- CFS is an MIT spinout with the goal of developing high-field HTS magnets for fusion energy and other applications.
- CFS is sponsoring research at MIT to develop the magnet technology.
- Part of this work includes developing numerical models to predict magnet performance, which will be validated against small-scale test magnets.
- Many parallels between simulating magnetized plasmas and superconducting magnets.



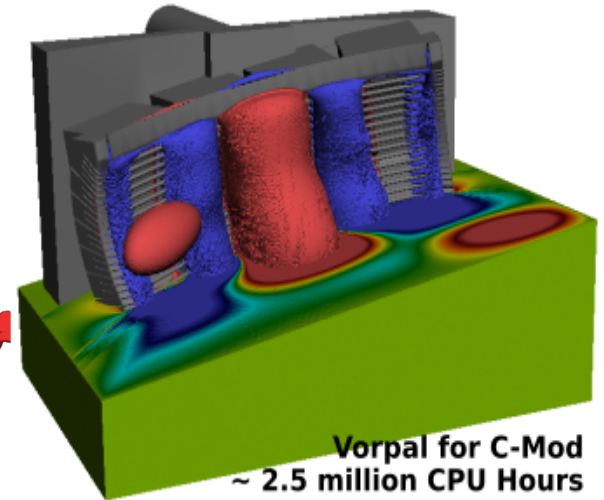
# Leading-class computing facilities allow for accurate RF wave physics simulations in core and edge regions with great detail



TORLH  
~ 1-10k CPU Hours



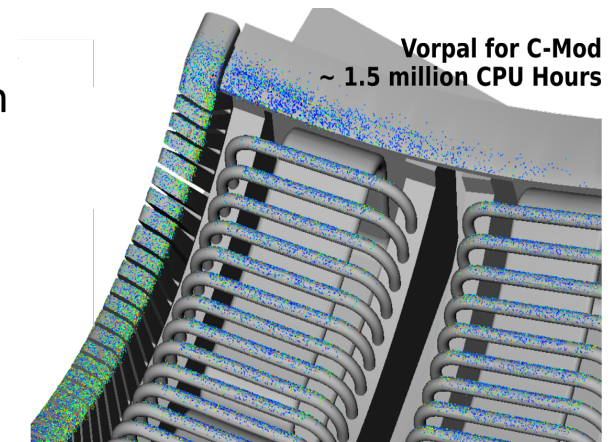
AORSA 3D for ITER  
~ 1 million CPU Hours



Vorpal for C-Mod  
~ 2.5 million CPU Hours

• These simulation models compute RF wave propagation and absorption including linear and non-linear effects using variety of numerical schemes

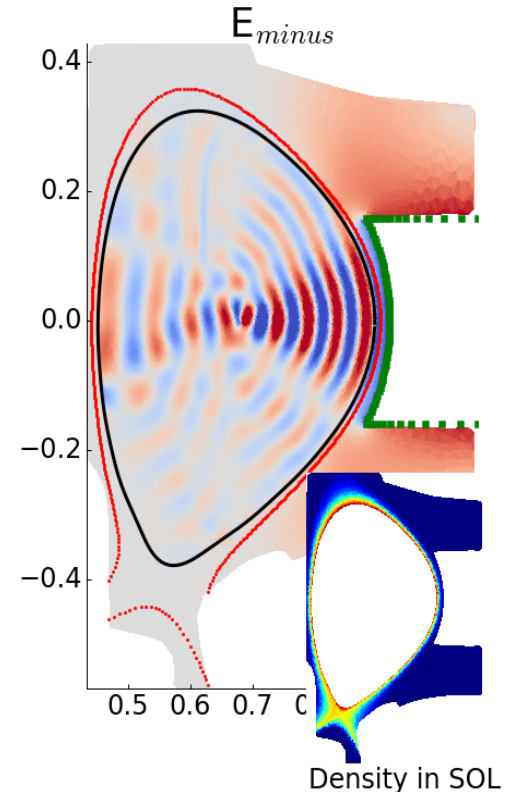
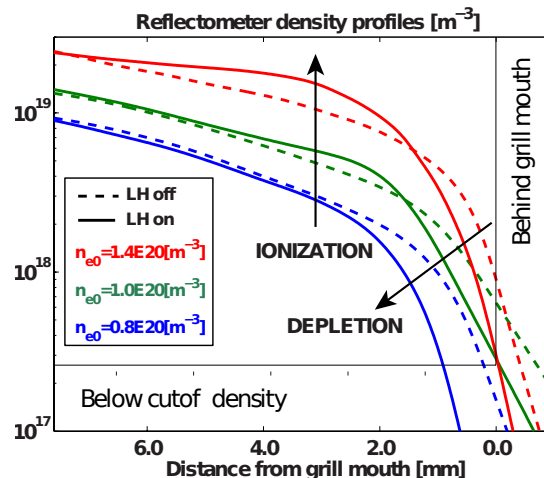
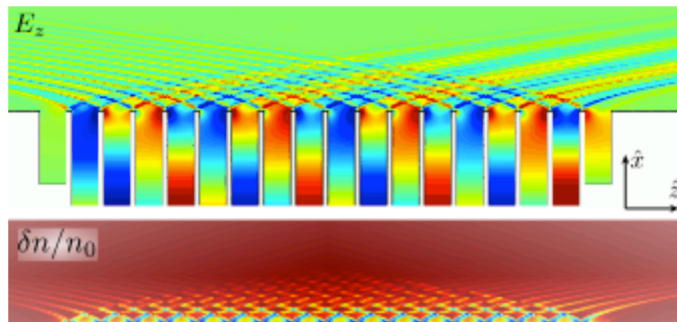
- **Spectral** code simulations of core LH and IC waves
- **FDTD (finite difference time domain)** simulation of ICRF antenna on C-Mod



Vorpal for C-Mod  
~ 1.5 million CPU Hours

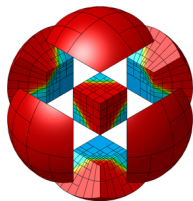
# FEM has been used to handle complicated geometry, multi-physics/code integration

- (right) FEM solution in edge is coupled with the core spectral solver solution
- (bottom) LH wave propagation near the antenna including
  - Ponderomotive force acting on plasma
  - Modification of  $n_e$



# Petra-M is developed on the MFEM library and applied to various RF wave problems in fusion plasmas

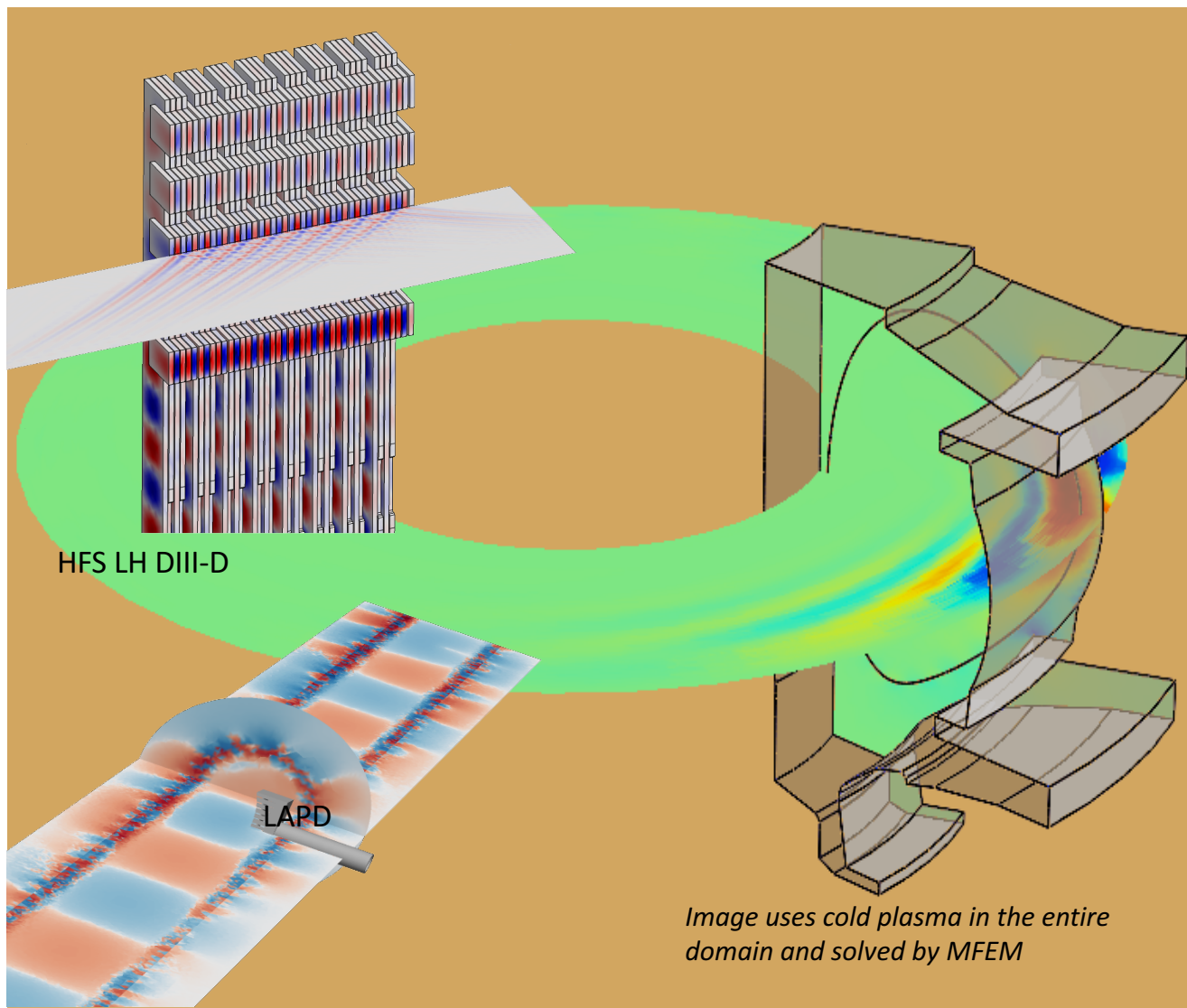
- Scalable MFEM library
- <http://mfem.org/features>



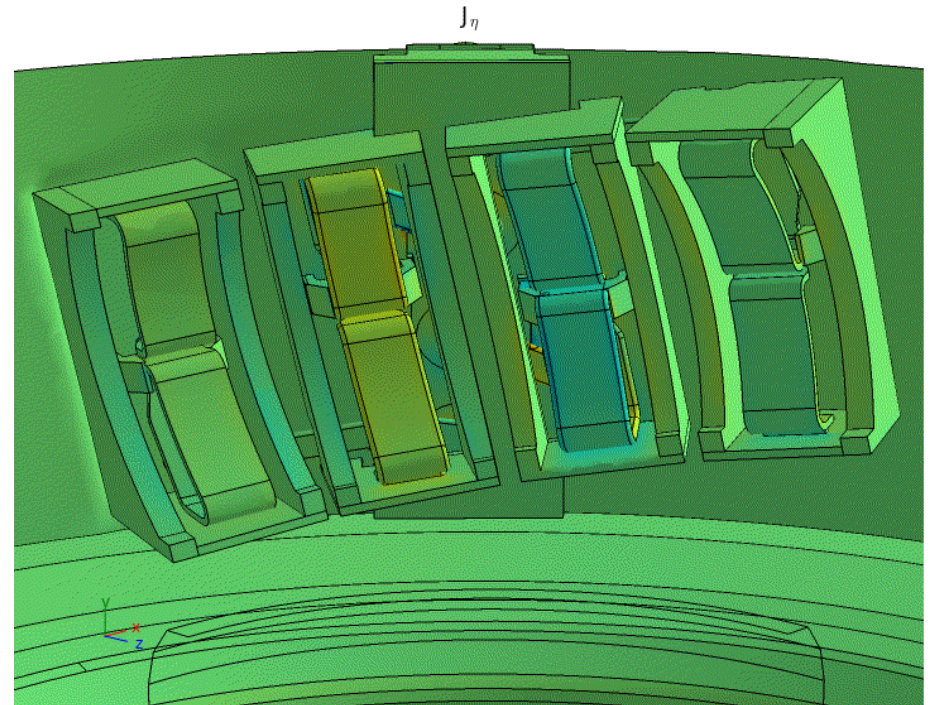
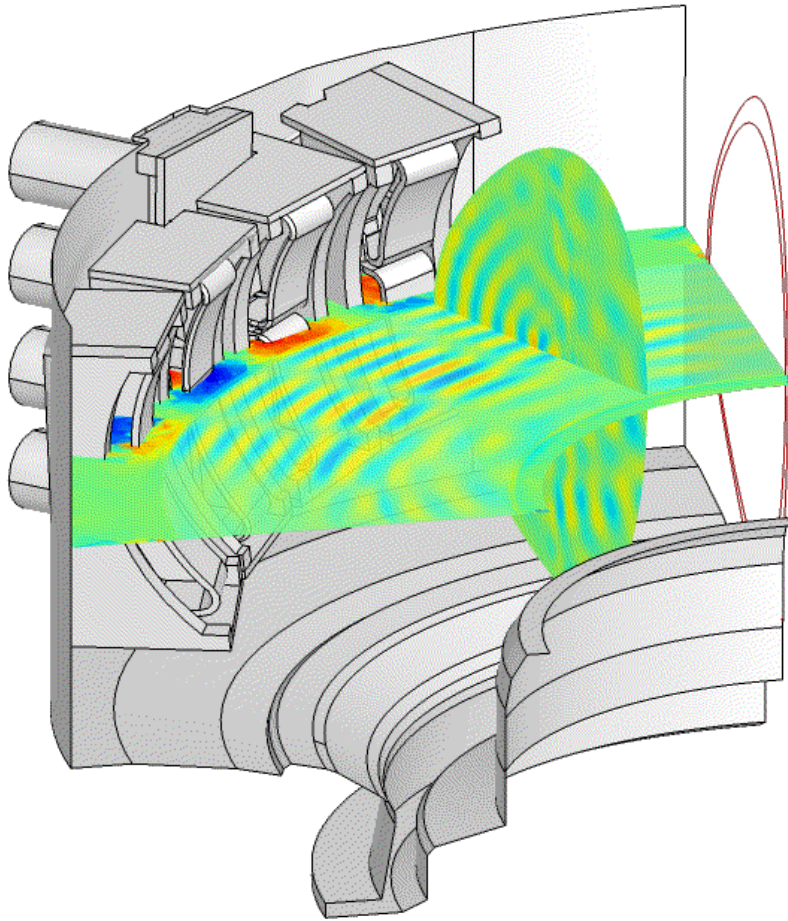
- Petra-M physics based FEM modeling interface

- Workflow management using  $\pi$ Scope

- <http://piscope.psfc.mit.edu>



# Petra-M was also coupled with the TORIC core spectral solver



- ICRF wave antenna propagation in the Alcator C-Mod tokamak
- Petra-M solves the RF field propagation in **cold** plasma near the antenna in 3D geometry
- TORIC solves the RF field propagation in **hot** core region

# Petra-M: Physics Equation Translator for MFEM

# MFEM

Lawrence Livermore National Laboratory



Free, lightweight, scalable C++ library for finite element methods. Supports arbitrary high order discretizations and meshes for a wide variety of applications.

- **Flexible discretizations on unstructured grids**

- Triangular, quadrilateral, tetrahedral and hexahedral meshes.
- Local conforming and non-conforming refinement.
- High-order mesh optimization (ASCR Base).
- Bilinear/linear forms for variety of methods: Galerkin, DG, DPG, ...

- **High-order methods and scalability**

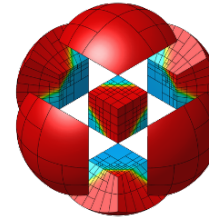
- Arbitrary-order H1, H(curl), H(div)- and L2 elements. Arbitrary order curvilinear meshes.
- MPI scalable to millions of cores. Enables application development on wide variety of platforms: from laptops to exascale machines.

- **Solvers and preconditioners**

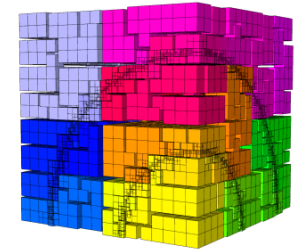
- Integrated with: HYPRE, SUNDIALS, PETSc, SUPERLU, ...
- Auxiliary-space AMG preconditioners for full de Rham complex

- **Open-source software**

- Open-source (GitHub) with thousands of downloads/year worldwide
- **Part of FASTMath, ECP/CEED, xSDK, OpenHPC, ...**



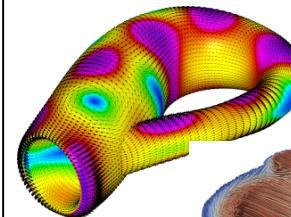
High order curved elements



Parallel non-conforming AMR



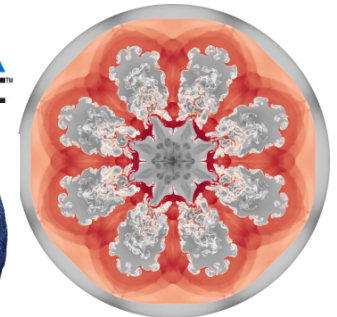
CEED  
EXASCALE DISCRETIZATIONS



Surface meshes



Heart modelling



Compressible flow ALE simulations

<http://mfem.org>



# MFEM provides building blocks to developing FEM application

```
1 import mfem
2 from mfem import intArray
3 import numpy as np
4
5 order = 1
6 mesh = mfem.Mesh('/Users/shiraiwa/mfem-3.1/data/beam-tet.mesh', 1,1)
7
8 dim = mesh.Dimension()
9 sdim = mesh.SpaceDimension
10 ref_levels = int(np.floor(np.log(50000./mesh.GetNE())/np.log(2.)/dim))
11 for x in range(ref_levels):
12     mesh.UniformRefinement()
13 mesh.ReorientTetMesh();
14 fec = mfem.ND_FECollection(order, dim)
15 fespace = mfem.FiniteElementSpace(mesh, fec)
16 print("Number of finite element unknowns: " + str(fespace.GetTrueVSize()))
17 ess_t dof_list = intArray();
18 if mesh.bdr_attributes.Size():
19     ess_bdr = intArray(mesh.bdr_attrib
20     ess_bdr = intArray([1]*mesh.bdr_attributes.Max())
21     fespace.GetEssentialTrueDofs(ess_bdr, ess_t dof_list);
22
23 from mfem.examples.ex3 import f_exact_cb, set_dim, set_freq
24 set_freq(1)
25 set_dim(3)
26 b = mfem.LinearForm(fespace);
27 f = mfem.VectorFunctionCoefficient(sdim, f_exact_cb);
28 dd = mfem.VectorFEDomainLFIntegrator(f);
29 b.AddDomainIntegrator(dd)
30 b.Assemble()
31 from mfem.examples.ex3 import E_exact_cb
32 x = mfem.GridFunction(fespace);
33 E = mfem.VectorFunctionCoefficient(sdim, E_exact_cb);
34 x.ProjectCoefficient(E);
35 muinv = mfem.ConstantCoefficient(1.0);
36 sigma = mfem.ConstantCoefficient(1.0);
37 a = mfem.BilinearForm(fespace);
38 a.AddDomainIntegrator(mfem.CurlCurlIntegrator(muinv));
```

Read Mesh File

Allocate FE space

Set Essential BC

Allocate Matrix and RHS

Fill Matrix and RHS

```
39 a.AddDomainIntegrator(mfem.VectorFEMassIntegrator(sigma));
40 static_cond = False
41 if (static_cond): a.EnableStaticCondensation()
42 a.Assemble();
43 A = mfem.SparseMatrix()
44 B = mfem.Vector()
45 X = mfem.Vector()
46 a.FormLinearSystem(ess_t dof_list, x, b, A, X, B);
47 ## Here, original version calls heghit, which is not
48 ## defined in the header...!?
49 print("Size of linear system: " + str(A.Size()))
50 M = mfem.GSSmoothing(A)
51 mfem.PCG(A, M, B, X, 1, 500, 1e-12, 0.0);
52 a.RecoverFEMSolution(X, b, x)
53 print("|| E_h - E ||_{L^2} = " + str(x.ComputeL2Error(E)))
54
```

Solve

$$\nabla \times \nabla \times E + E = f$$

$$\downarrow$$
$$M x = b$$

In a short ~60 lines, it does...

- Define Finite Element Function Space
- Matrix Assembly/Solve

Changes required for parallelize the code is small.

# PyMFEM (MFEM Python-binding) is developed for rapid development

- Allows for construct, manipulate MFEM c++ objects
- Supports both parallel (with MPI) and serial (w/o MPI) MFEM
- Allows for defining FunctionCoefficient using python class
- (Partial) Supports passing numpy array as argument and return value

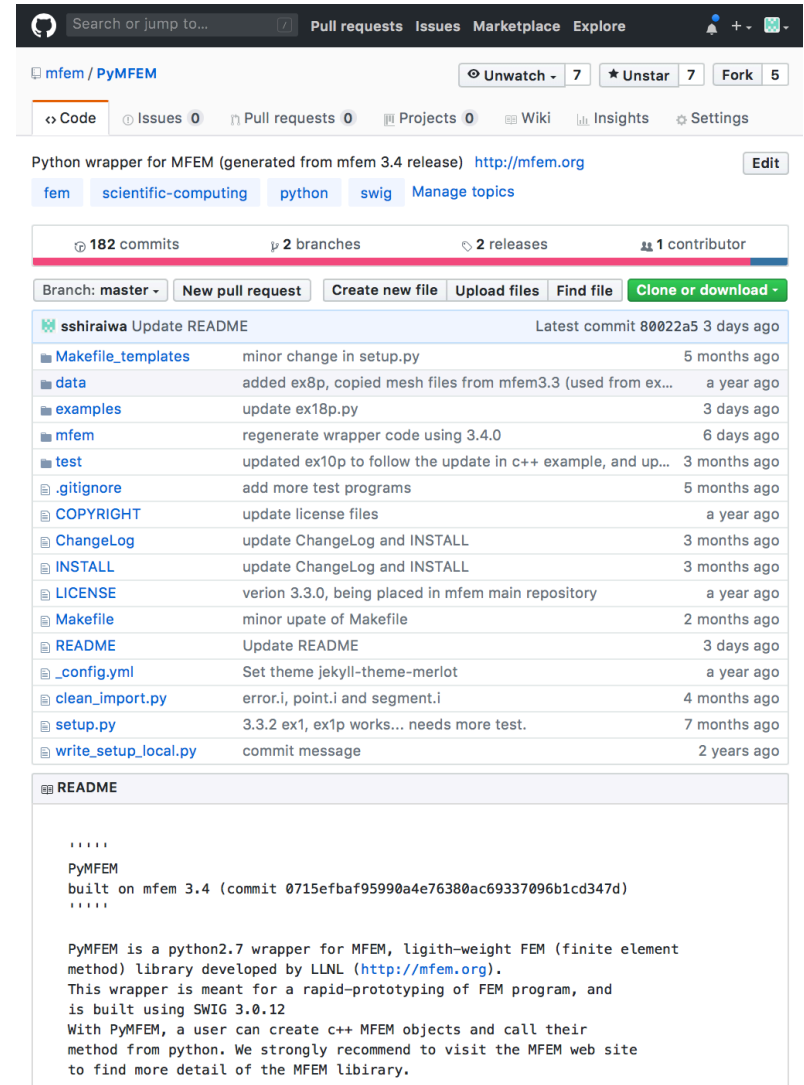
(c++)

```
double data[] = {1,2,3};  
o = Vector (data, 3);
```

(python)

```
v = mfem.Vector(np.array([1,2,3.]))
```

- Create HypreParCSR/HypreVector using distributed scipy.sparse matrix



mfem / PyMFEM

Python wrapper for MFEM (generated from mfem 3.4 release <http://mfem.org>)

182 commits 2 branches 2 releases 1 contributor

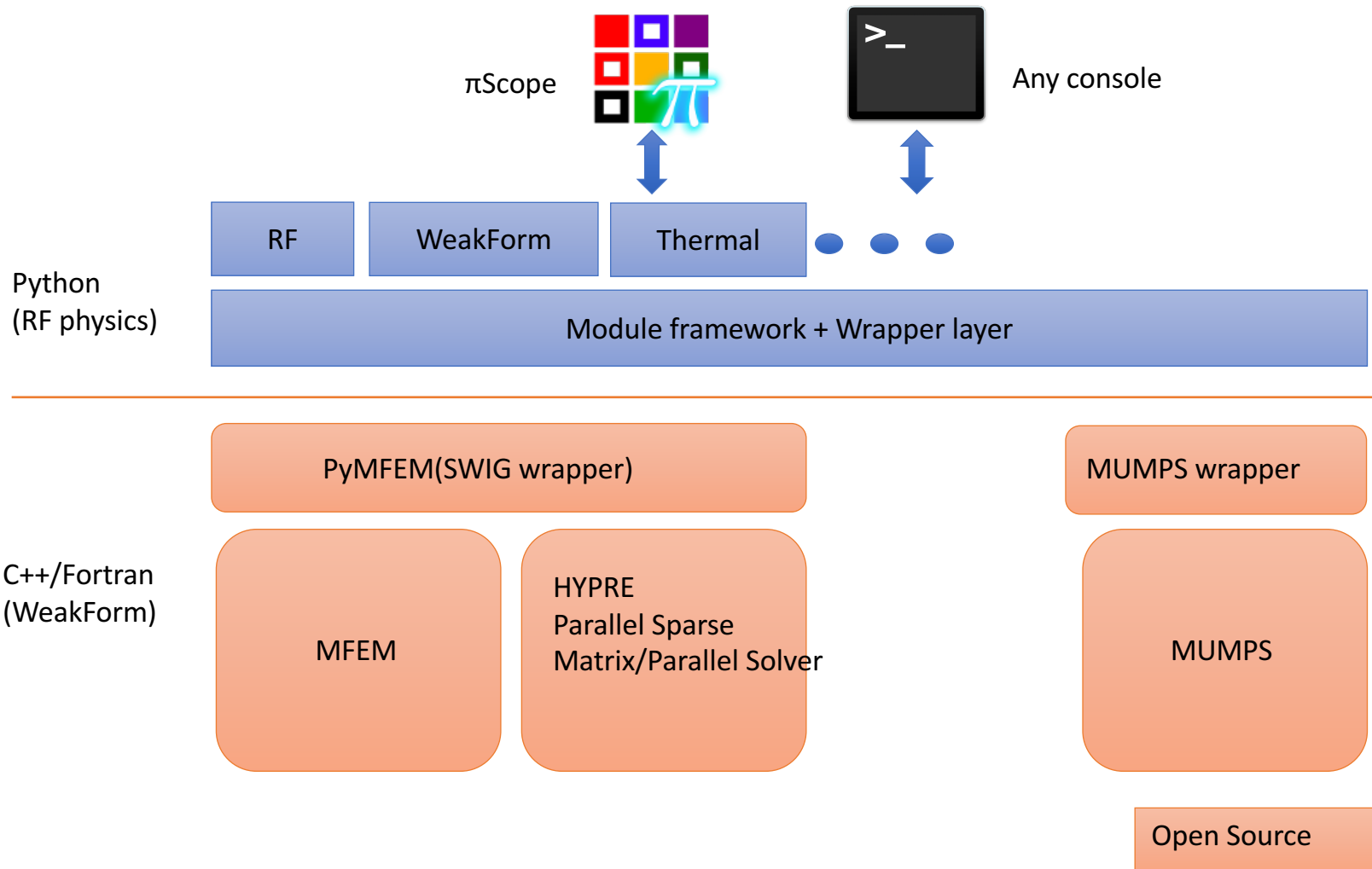
File	Description	Last Commit
Makefile_templates	minor change in setup.py	5 months ago
data	added ex8p, copied mesh files from mfem3.3 (used from ex...	a year ago
examples	update ex18p.py	3 days ago
mfem	regenerate wrapper code using 3.4.0	6 days ago
test	updated ex10p to follow the update in c++ example, and up...	3 months ago
.gitignore	add more test programs	5 months ago
COPYRIGHT	update license files	a year ago
ChangeLog	update ChangeLog and INSTALL	3 months ago
INSTALL	update ChangeLog and INSTALL	3 months ago
LICENSE	verion 3.3.0, being placed in mfem main repository	a year ago
Makefile	minor upate of Makefile	2 months ago
README	Update README	3 days ago
_config.yml	Set theme jekyll-theme-merlot	a year ago
clean_import.py	error.i, point.i and segment.i	4 months ago
setup.py	3.3.2 ex1, ex1p works... needs more test.	7 months ago
write_setup_local.py	commit message	2 years ago

README

```
.....  
PyMFEM  
built on mfem 3.4 (commit 0715efbaf95990a4e76380ac69337096b1cd347d)  
.....  
  
PyMFEM is a python2.7 wrapper for MFEM, ligith-weight FEM (finite element  
method) library developed by LLNL (http://mfem.org).  
This wrapper is meant for a rapid-prototyping of FEM program, and  
is built using SWIG 3.0.12  
With PyMFEM, a user can create c++ MFEM objects and call their  
method from python. We strongly recommend to visit the MFEM web site  
to find more detail of the MFEM library.
```

Availale from GitHub (LGPL)

# Petra-M uses Python for rapid physics module development, while using scalable FEM and solver libraries



# Model setup interface is built on $\pi$ Scope

- $\pi$ Scope

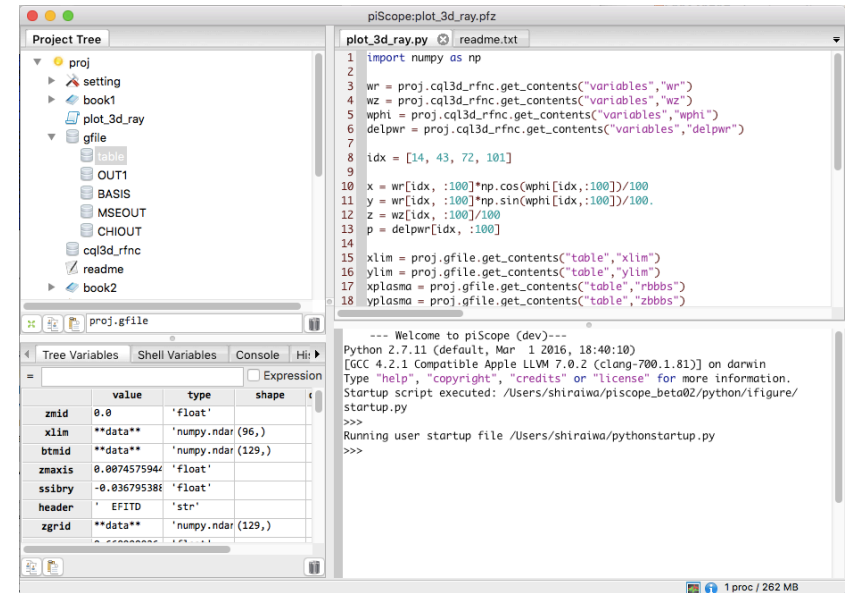
- All-in-one style python data analysis environment

- Shell
- Editor
- Debugger
- Project management
- Data Browser

- Interactive plotting environment

- Based on matplotlib + custom GUIs to edit figure
- OpenGL based 3D graphics

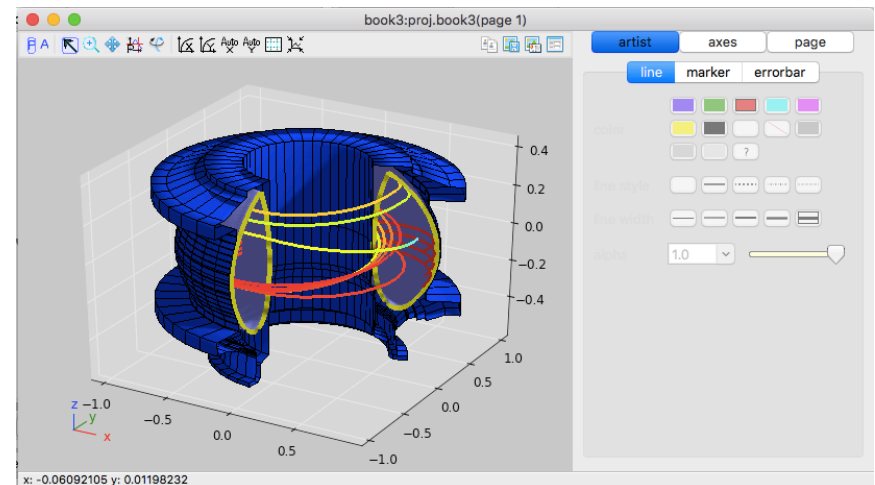
- Native support to browse MDSplus data system
- Components to support code integration
- Open Source (GNUv3)



The screenshot shows the piScope IDE interface. On the left is a Project Tree with folders like 'proj', 'setting', 'book1', 'plot\_3d\_ray', 'gfile', 'table', 'OUT1', 'BASIS', 'MSEOUT', 'CHIOU', 'cq13d\_rfunc', 'readme', and 'book2'. The main window is split into a code editor and a console. The code editor shows Python code for plotting a 3D model. The console shows the Python startup message and the execution of a startup script.

```
1 import numpy as np
2
3 wr = proj.cq13d_rfunc.get_contents("variables","wr")
4 wz = proj.cq13d_rfunc.get_contents("variables","wz")
5 wphi = proj.cq13d_rfunc.get_contents("variables","wphi")
6 delpwr = proj.cq13d_rfunc.get_contents("variables","delpwr")
7
8 idx = [14, 43, 72, 101]
9
10 x = wr[idx, :100]*np.cos(wphi[idx,:100])/100
11 y = wr[idx, :100]*np.sin(wphi[idx,:100])/100.
12 z = wz[idx, :100]/100
13 p = delpwr[idx, :100]
14
15 xlim = proj.gfile.get_contents("table","xlim")
16 ylim = proj.gfile.get_contents("table","ylim")
17 xplasma = proj.gfile.get_contents("table","rbbbs")
18 yplasma = proj.gfile.get_contents("table","zbbbs")
```

--- Welcome to piScope (dev)---  
Python 2.7.11 (default, Mar 1 2016, 18:40:10)  
[GCC 4.2.1 Compatible Apple LLVM 7.0.2 (clang-700.1.81)] on darwin  
Type "help", "copyright", "credits" or "license" for more information.  
Startup script executed: /Users/shiraiwa/piscope\_beta02/python/figure/  
startup.py  
>>> Running user startup file /Users/shiraiwa/pythonstartup.py  
>>>



### piScope:test4\_3d\_2\_final.pfz\*

File Edit View Plot Help

Project Tree

- axes1 (L:0.00 B:0.00 W:1.00 H:1.00)
- face\_1
- face\_2
- face\_3
- face\_4
- face\_5
- face\_6
- face\_7

Tree Variables Shell Variables Console History

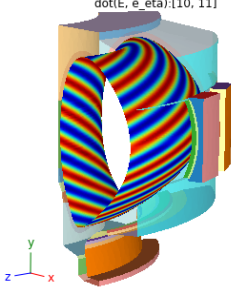
value	type	shape
kwds {}	'dict'	

```
205     return P*sin(phi)**2*sin(theta)**2 - S*sin(phi)**2*sin(theta)**2
206
207 @variable.array(complex = True, shape=(3,3))
208 def epsilon_pl(x, y, z):
209     Br, Bz, Bt = Bfield(x, y, z)
210     Bnorm = sqrt(Br**2+Bz**2+Bt**2)
211
212     #
213     By = Bz
214     Bz = -Bt
215     Bx = Br
216     import numpy as np
217     B = np.array([Bx, By, Bz]).reshape(3,1)
218     nhi = xvz2nhi(x, y, z)
```

### proj.book4(frame 0)

File Edit View Plot Help

artist axes page

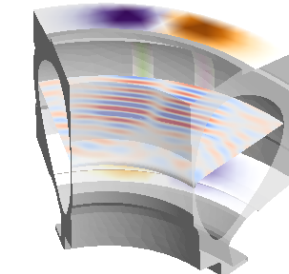


canvas size = (331, 356)

### proj.book2(frame 25)

File Edit View Plot Help

artist axes page



common x y z c c2 c3 gl

label Style...

range -0.6 auto margin  
0.6 int sym

scale 10.0  
1.0 1.0

### mfembook:proj.model2.mfem.mfe

File Edit View Plot MFEM Help

Model Tree

- General(NS:global)
- Mesh
- Phys
- EM3D1(NS:toric)
- Domain
- Vac1
- Div1
- Div2
- Anisotropic
- Anisotropic
- Boundary
- PEC1
- Surf1
- Surf2
- Continuity:
- H1
- PMC1
- E1
- Pair
- Solver

Config. Selection

epsilon\* Array Form

=epsilon\_pl

mur\* Elemental Form

1.0	0.0	0.0
0.0	1.0	0.0
0.0	0.0	1.0

sigma\* Elemental Form

0.0	0.0	0.0
0.0	0.0	0.0
0.0	0.0	0.0

### plot...

GeomBdr Edge Bdr Bdr(arrow) Slice Config

Expression

Expression(x)

Edge all

Physics Phys.EM3D1

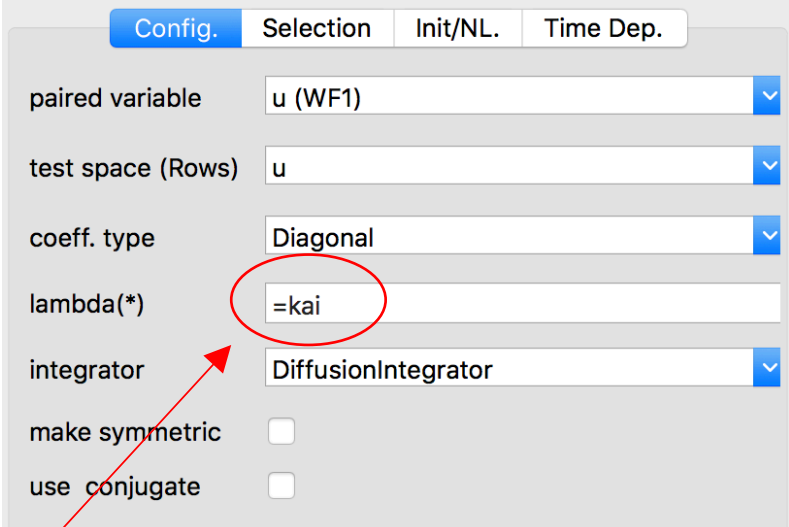
dynamic extraction

merge solutions

Export Apply

# Material properties in Petra-M

- Material property can be defined by using a Python function + decorator
  - A Python decorator specifies the type (float/complex) and shape of returned value
  - Supports Spatial dependence.
  - MFEM calls this function with the special coordinates at quadrature integration points.
  - Can use a value from a solution from the previous solve step.



The screenshot shows a configuration window for a material property. It has four tabs: 'Config.' (selected), 'Selection', 'Init/NL.', and 'Time Dep.'. The 'Config.' tab contains several settings:

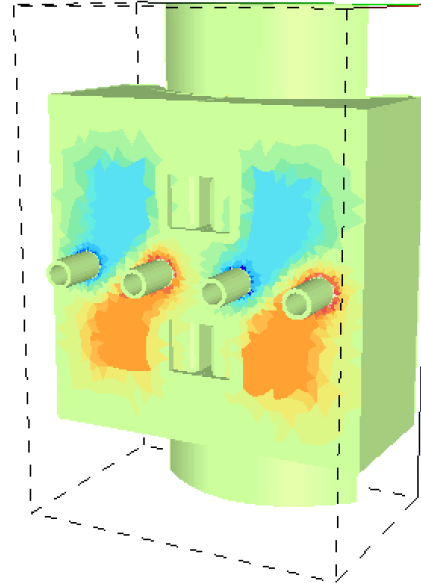
- paired variable: u (WF1)
- test space (Rows): u
- coeff. type: Diagonal
- lambda(\*): =kai (circled in red)
- integrator: DiffusionIntegrator
- make symmetric:
- use conjugate:

A red arrow points from the circled '=kai' value in the configuration window to the Python code block below.

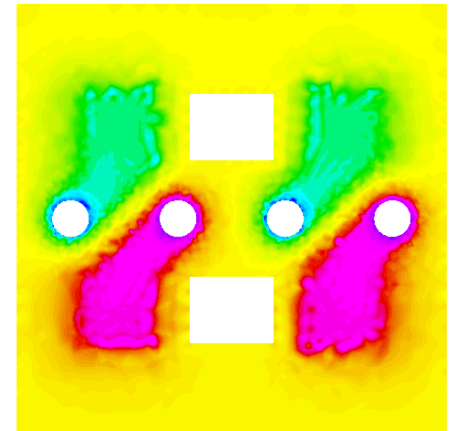
```
1 import numpy as np
2 from petram.helper.variables import variable
3
4 @variable.array(complex=False, shape=(3,))
5 def kai(x, y, z):
6     return np.array([1., 0.1, 0.1])
7
```

# Mesh extension and DoF projection/mapping

- We often need to handle the coupling of PDEs defined over geometrically different regions
  - (Example) RF propagation in waveguide (RF) and heating of waveguide (heat)
- Petra-M generates automatically daughter meshes.
  - Daughter meshes inherit domain/boundary attributes for the mother mesh.
  - DoF mapping operator (can be either projection or linear solve.)
  - Works for H1/ND/RT elements.
  - Supports arbitrary polynomial order.
  - Supports a curved mesh.



RF wave field is induced on the metal wall of antenna box.



- Perpendicular electric field on the surface, generated by mapping 3D RF field

# RF module (frequency domain Maxwell prob.)

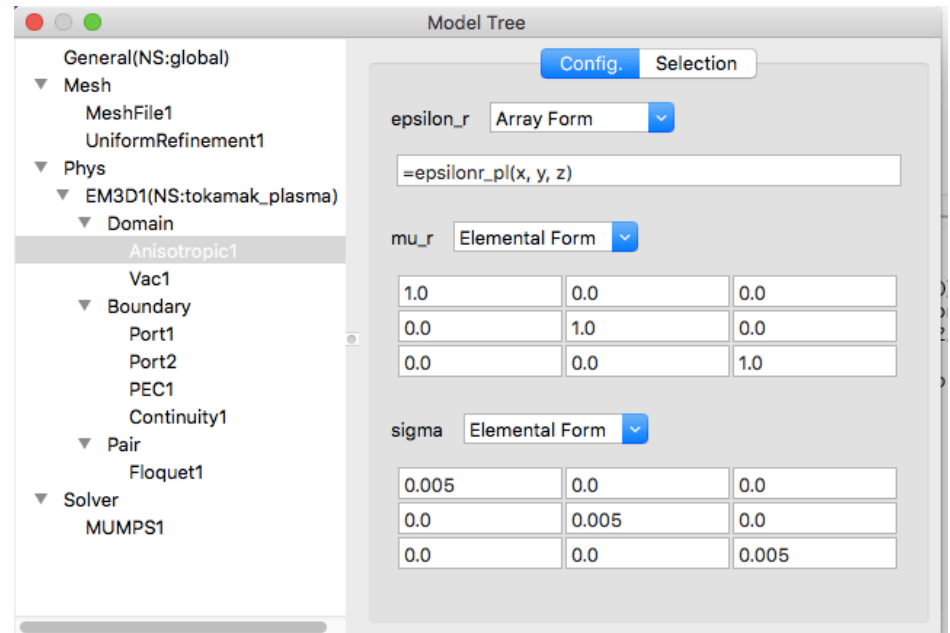
Maxwell eq.

$$\begin{aligned} \nabla \times (\mu^{-1} \nabla \times \mathbf{E}) - (\omega^2 \epsilon - j\omega\sigma) \mathbf{E} &= -j\omega \mathbf{J}^s \text{ in } S, \\ \hat{\mathbf{n}} \times \mathbf{E} &= \mathbf{P} \text{ on } L_1, \\ \hat{\mathbf{n}} \times (\mu^{-1} \nabla \times \mathbf{E}) + \gamma \hat{\mathbf{n}} \times \hat{\mathbf{n}} \times \mathbf{E} &= \mathbf{Q} \text{ on } L_2. \end{aligned}$$

Weak form

$$\begin{aligned} \int_S [\mu^{-1} (\nabla \times \mathbf{W}_i) \cdot (\nabla \times \mathbf{E}) - (\omega^2 \epsilon - j\omega\sigma) \mathbf{W}_i \cdot \mathbf{E}] dS \\ + \int_{L_2} \mathbf{W}_i \cdot (\mathbf{Q} - \gamma \hat{\mathbf{n}} \times \hat{\mathbf{n}} \times \mathbf{E}) dl = -j\omega \int_S \mathbf{W}_i \cdot \mathbf{J}^s dS. \end{aligned}$$

- Domain
  - Uniform dielectric media
  - Anisotropic (matrix) media
  - External J
  - DivJ constraints in vacuum
- Boundary
  - Perfect electric conductor ( $E_t=0$ )
  - Perfect magnetic conductor ( $B_t=0$ )
  - Waveguide port (TE, TEM modes)
  - Periodic boundary
  - Surface current/Magnetic field/Electric field





# WF (weak form) module

- Used to construct an FEM model by specifying MFEM integrators (right)
- Can be coupled with other physics simulation model to define multi-physics coupling.

## Scalar Field Operators

These operators require scalar-valued trial spaces. Many of these operators will work with either H1 or L2 basis functions but some that require a gradient operator should be used with H1.

## Square Operators

These integrators are designed to be used with the BilinearForm object to assemble square linear operators.

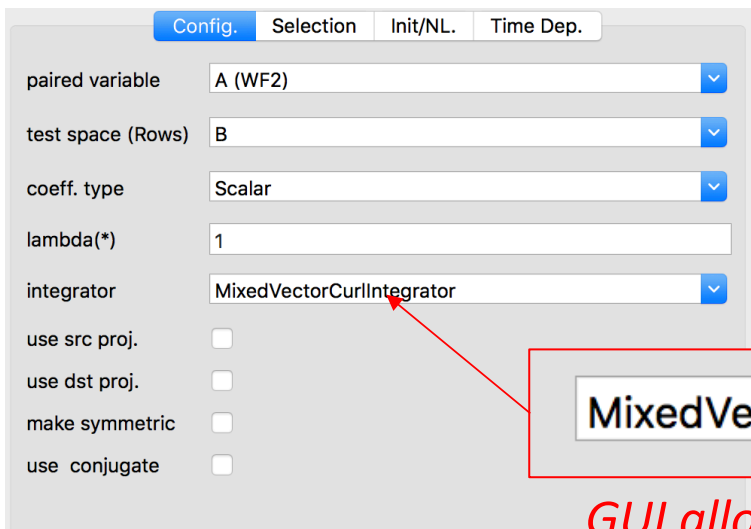
Class Name	Spaces	Coef.	Operator	Continuous Op.	Dimension
MassIntegrator	H1, L2	S	$(\lambda u, v)$	$\lambda u$	1D, 2D, 3D
DiffusionIntegrator	H1	S, M	$(\lambda \nabla u, \nabla v)$	$-\nabla \cdot (\lambda \nabla u)$	1D, 2D, 3D

## Mixed Operators

These integrators are designed to be used with the MixedBilinearForm object to assemble square or rectangular linear operators.

Class Name	Domain	Range	Coef.	Operator	Continuous Op.	Dimension
MixedScalarMassIntegrator	H1, L2	H1, L2	S	$(\lambda u, v)$	$\lambda u$	1D, 2D, 3D
MixedScalarWeakDivergenceIntegrator	H1, L2	H1	V	$(-\vec{\lambda} u, \nabla v)$	$\nabla \cdot (\vec{\lambda} u)$	2D, 3D
MixedScalarWeakDerivativeIntegrator	H1, L2	H1	S	$(-\lambda u, \frac{dv}{dx})$	$\frac{d}{dx}(\lambda u)$	1D
MixedScalarWeakCurlIntegrator	H1, L2	ND	S	$(\lambda u, \nabla \times \vec{v})$	$\nabla \times (\lambda u \hat{z})$	2D
MixedVectorProductIntegrator	H1, L2	ND, RT	V	$(\vec{\lambda} u, \vec{v})$	$\vec{\lambda} u$	2D, 3D
MixedScalarWeakCrossProductIntegrator	H1, L2	ND, RT	V	$(\vec{\lambda} u \hat{z}, \vec{v})$	$\vec{\lambda} \times \hat{z} u$	2D

See <http://mfem.org/bilininteg/> and <http://mfem.org/lininteg/> for the full list



GUI allows to pick an MFEM integrator from menu

# Solver

- Petra-M supports variety of linear solvers through MFEM library
- Linear Solvers
  - Direct solver:
    - MUMPS/Strumpack.
  - Iterative solver:
    - Krylov subspace solvers from Hypre (CG, MINRES, GMRES, FGMRES, BiCGSTAB...)
    - Block preconditioner GUI
- A user can construct a solution sequence, which is made from multiple linear-solve/time dependent solver runs.

GMRES

log\_level: 1

max iter.: 200

rel. tol.: 1e-07

abs. tol.: 1e-07

restart(kdim): 50

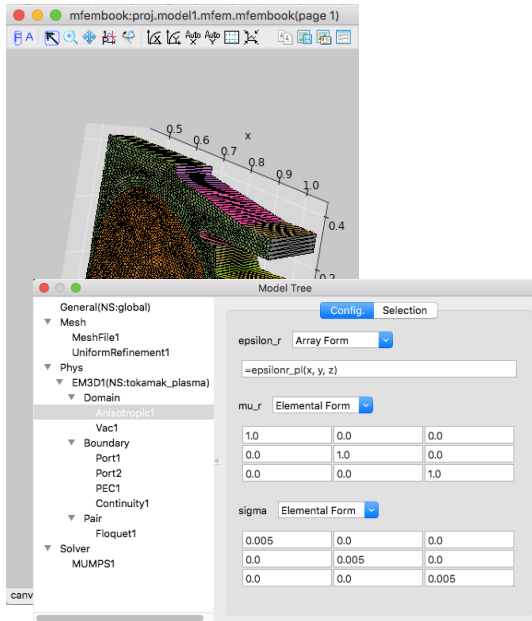
advanced mode

preconditioner: D

```
3 @prc.blk_diagonal
4 def D(p, g, *args, **kwargs):
5     GSgen.set_param(g, "v")
6     gs = GSgen()
7     k = g.get_row_by_name("v")
8     p.SetDiagonalBlock(k, gs) # set to block
9     return p
```

*Custom preconditioner can be defined using a Python decorator*

# Petra-M runs on a laptop, but also allows for submitting a job to a cluster



Model data files



Solutions/Processed data



- User frontend is used define a simulation mode using physics interface.
- Simulation model is “preprocessed” to make input files
  - Resolve boundary index
  - Analyze geometry data
- Input files are Python scripts, allowing for modifying the model on a server before running.

HTS modeling efforts

# Goal: adopt a framework for simulating RF in plasmas to static and dynamic HTS magnet systems

- Many commonality between HTS and waves in plasmas
  - Highly anisotropic and non-linear material properties
  - Complex geometry
  - Maxwell's equations and heat transport
  - FEM Libraries demonstrated to run a large scale clusters
  - GUI sets supporting, multi-physics modeling
- Challenge
  - HTS tape is extremely thin compared to the size of magnet.
  - HTS exhibits strongly anisotropic and non-linear material property.

$$\nabla \times \left( \frac{1}{\mu} \nabla \times \vec{A} \right) = \vec{\sigma} (T, \vec{B}, \vec{J}) \vec{E}$$

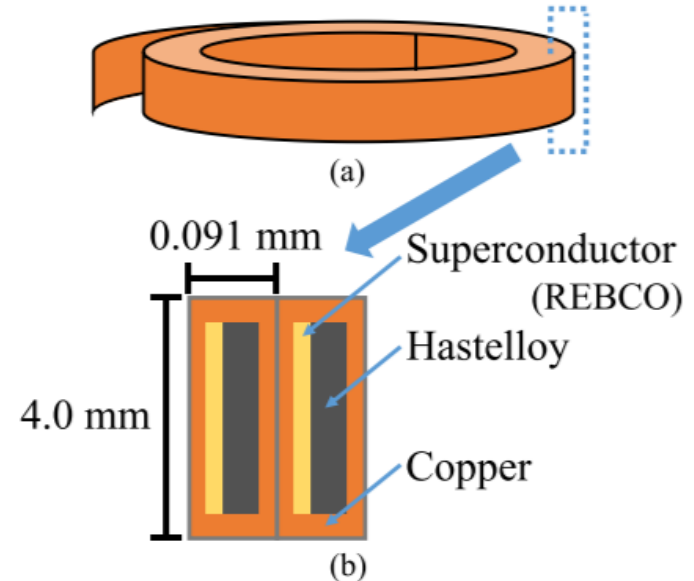
$$\nabla(\vec{\sigma} \vec{E}) = 0, \nabla \cdot \vec{A} = 0$$

$$\vec{E} = -\frac{d\vec{A}}{dt} - \nabla\phi, \vec{B} = \nabla \times \vec{A}$$

$$\rho C_p \frac{dT}{dt} - \nabla \vec{k} \nabla T = q, \text{ where } q = \vec{E} \cdot \vec{J}$$

# Approach - Hierarchy of models

- Microscopic to Macroscopic properties
  - Investigate how stacks of tapes with different internal materials manifest thermal and electrical conductivity. See eg [Noguchi 2016 TAS]
  - This model to minimize peak voltages and heating
- Continuous media approximation
  - Circular cross section double pancake geometry
  - Tape not explicit in geometry.
    - Anisotropic electric conductivity
    - Rotate conductivity tensor to align with 'tape' position locally
      - Tape is on a spiral with finite pitch so there is a radial component
    - Uniform thermal conductivity from copper matrix



## Summary

- Petra-M framework is being developed
  - Based on the scalable MFEM finite element library.
  - Developed originally to solve the frequency domain Maxwell problem in order to model RF propagation in a cold plasma.
  - Extended to run more complicated multi-physics type simulations.
- Application to HTS tape based magnet modeling has started, aiming towards,
  - Quench propagation analysis.
  - Magnet performance Analysis in whole tokamak device scale.